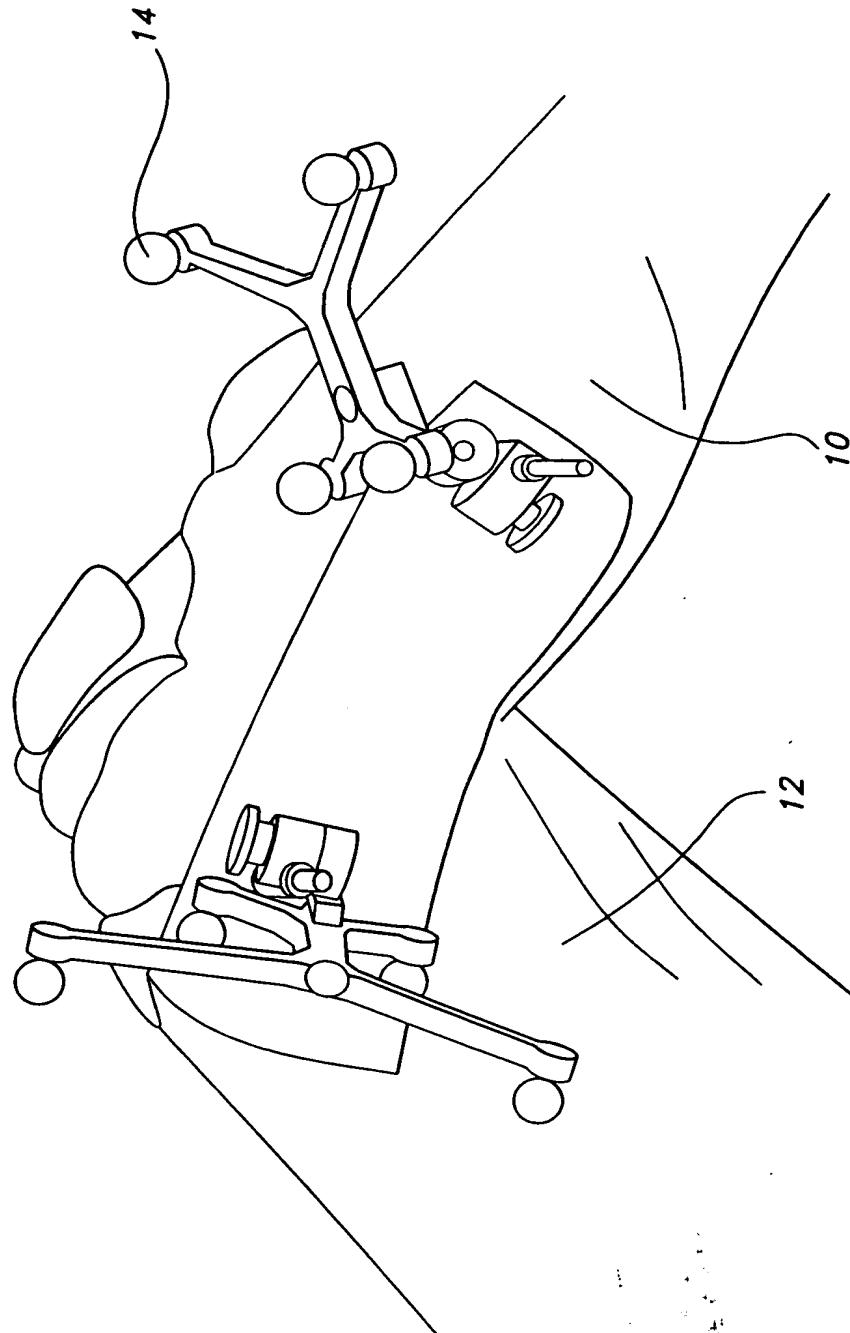




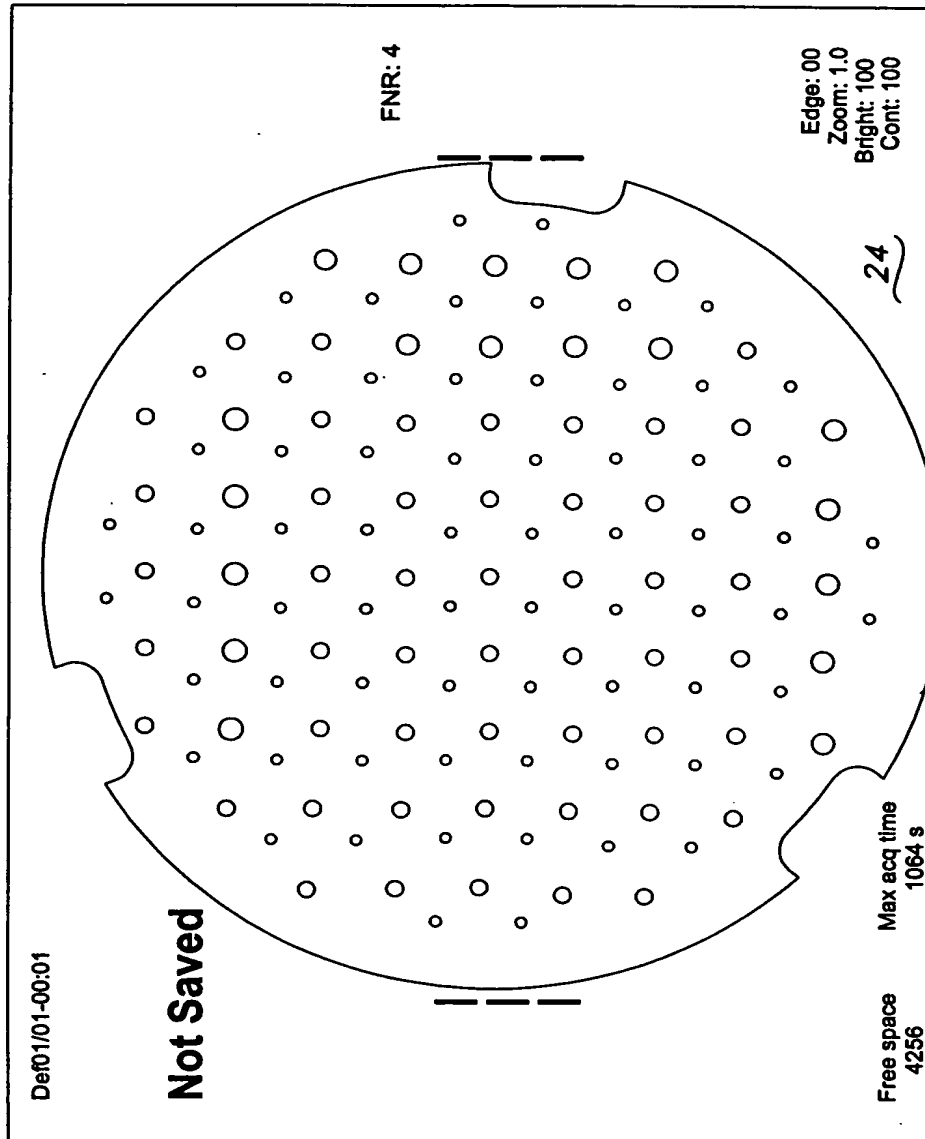
**FIG 1**

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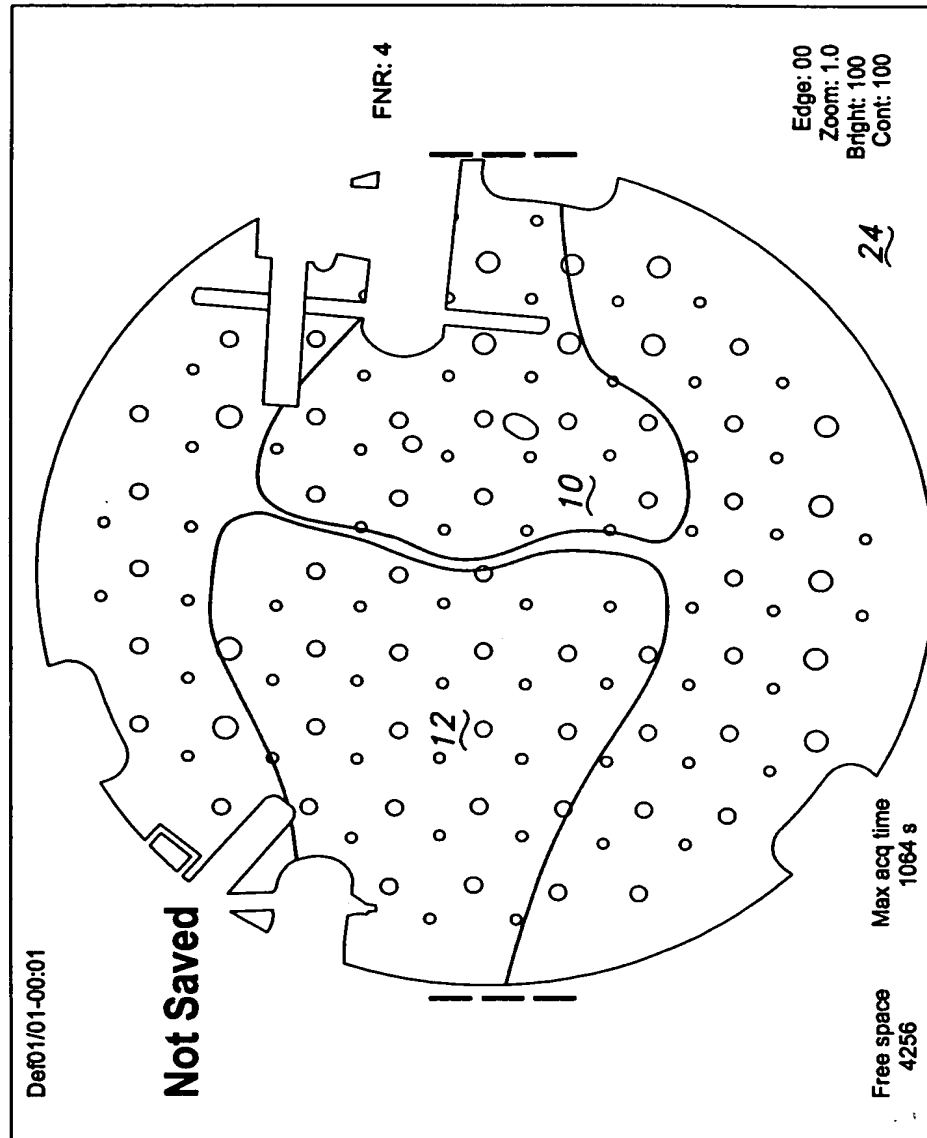
**FIG 2**

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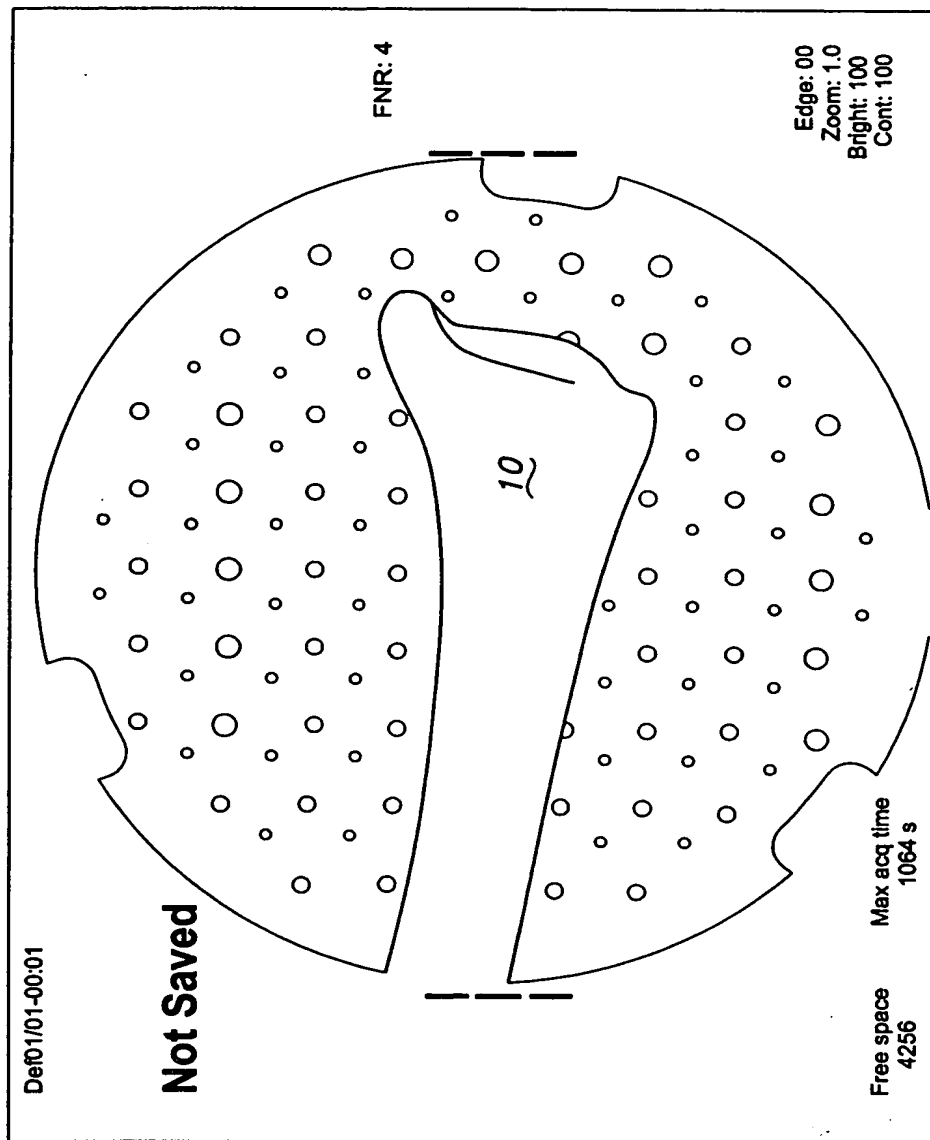
**FIG 4**

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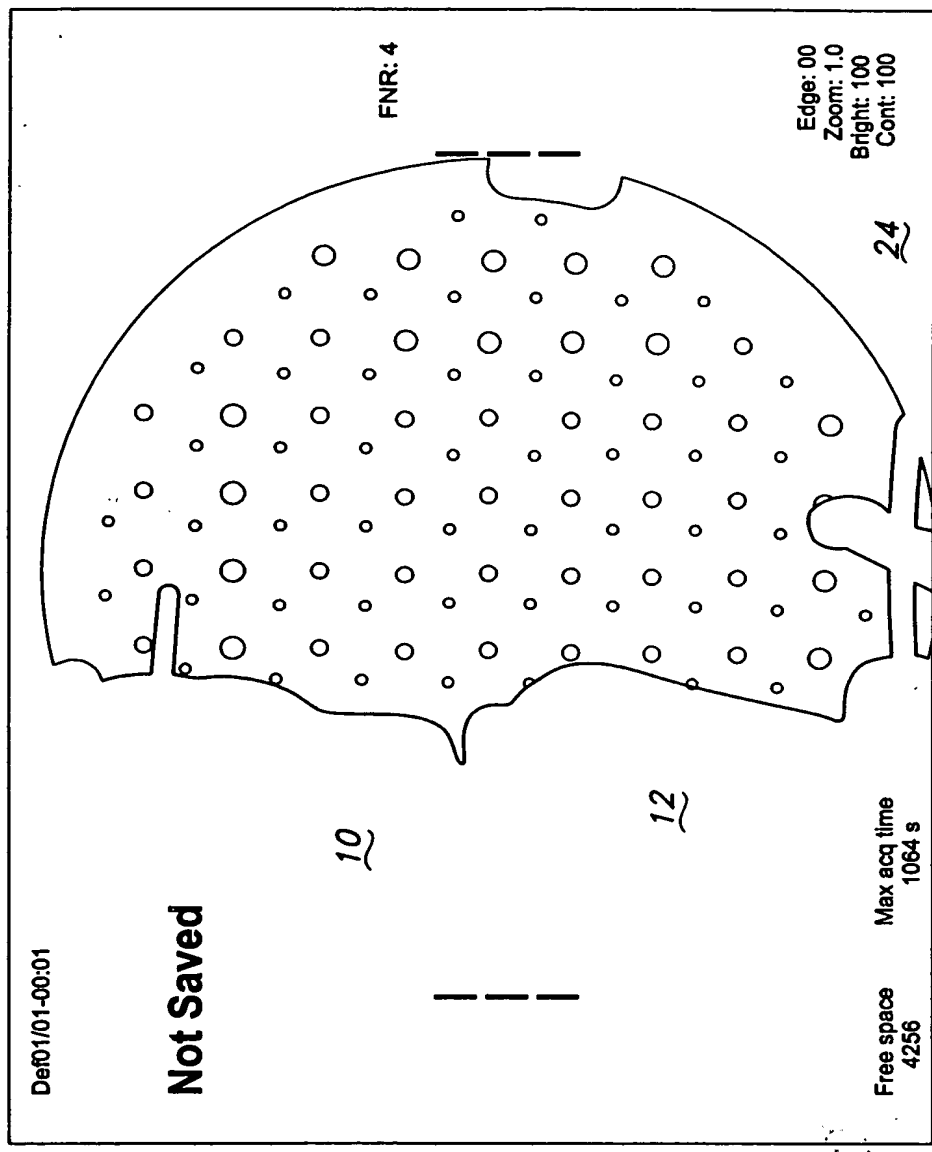
**FIG 6**

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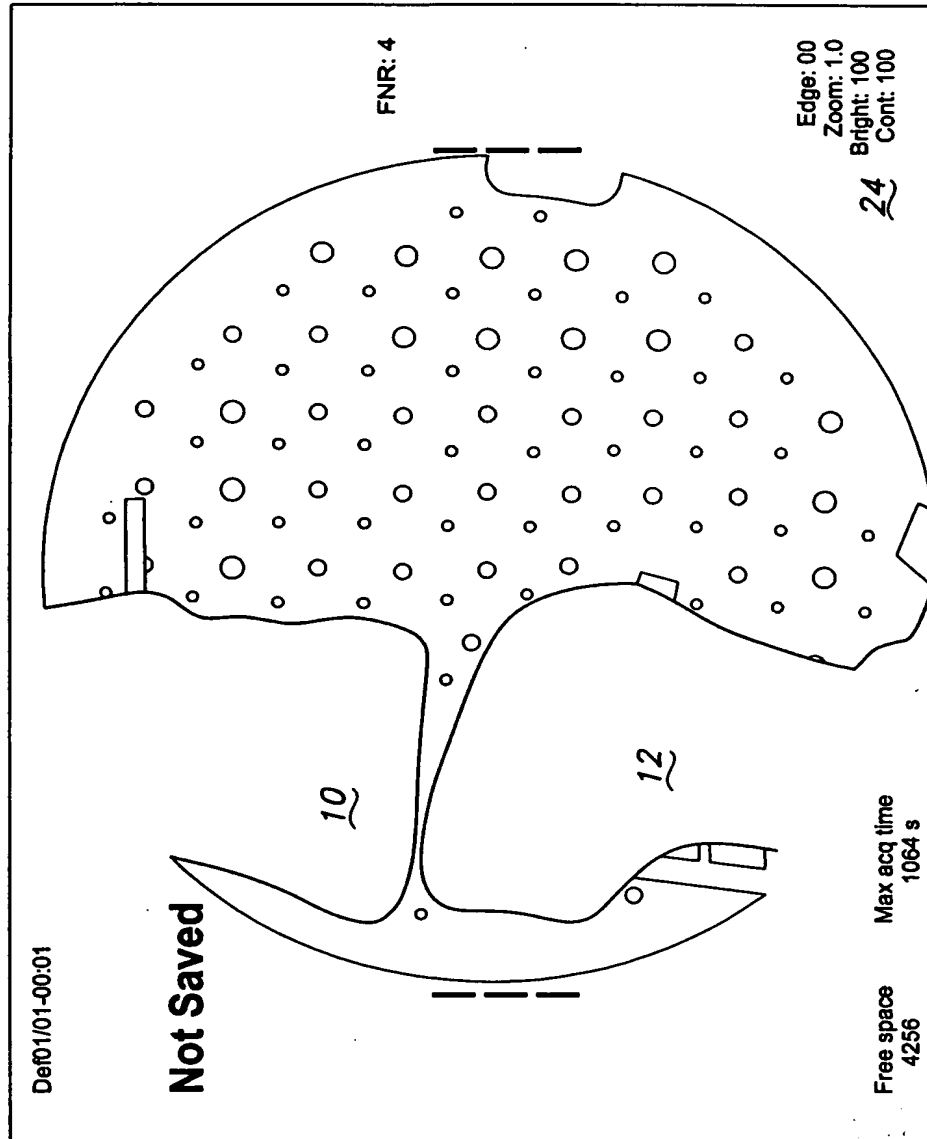
**FIG 7**

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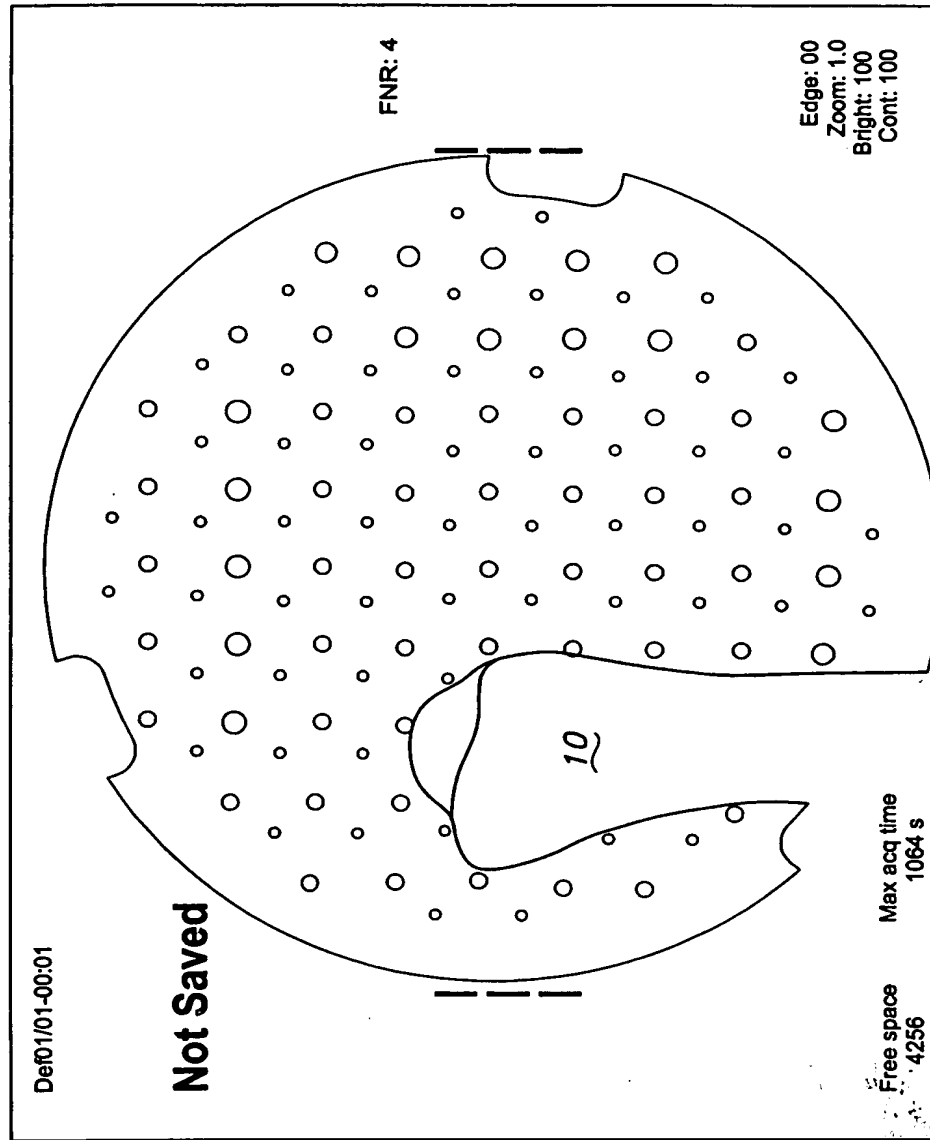
**FIG. 8**

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**FIG 9**

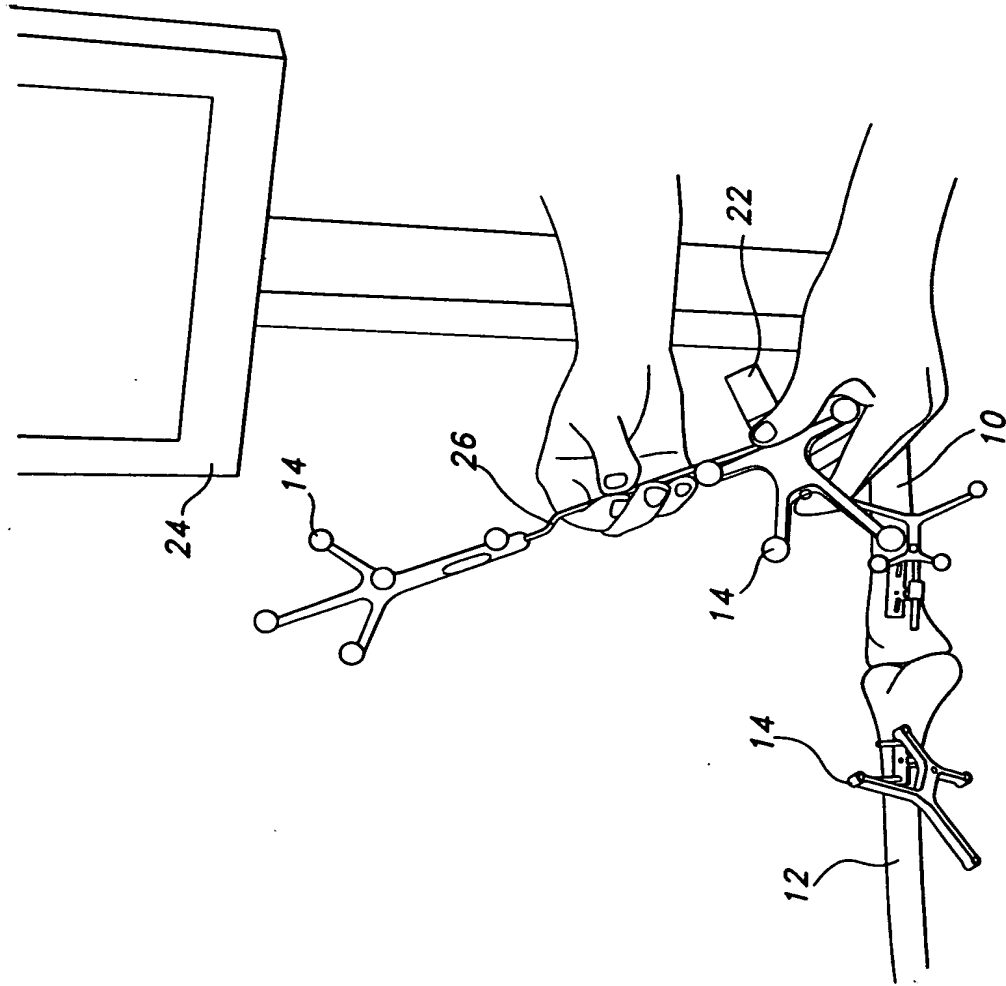
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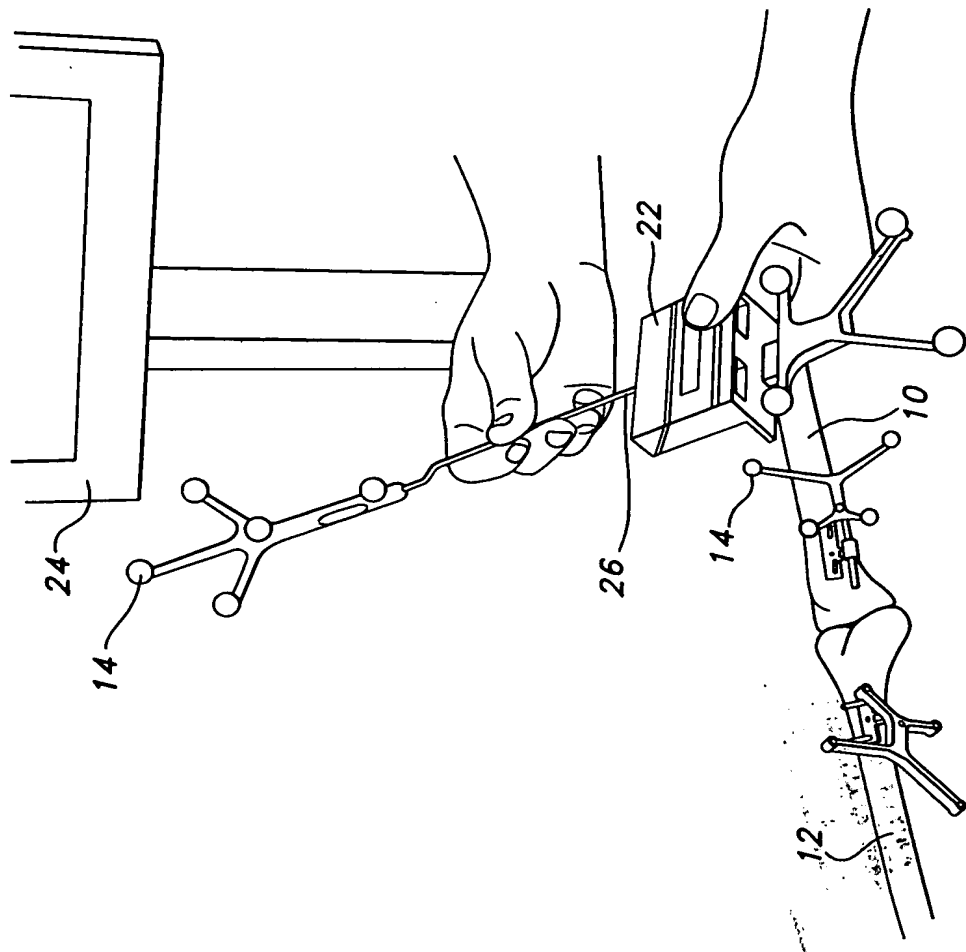
**FIG 10**



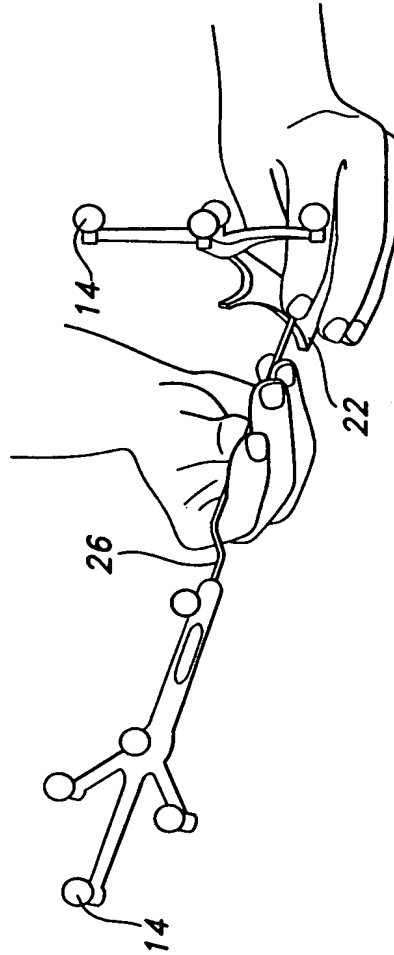
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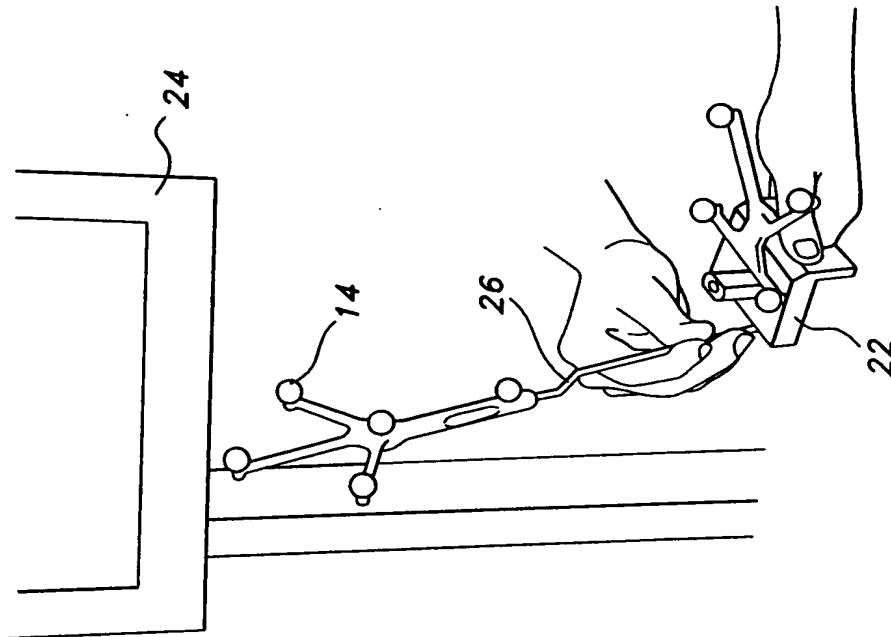


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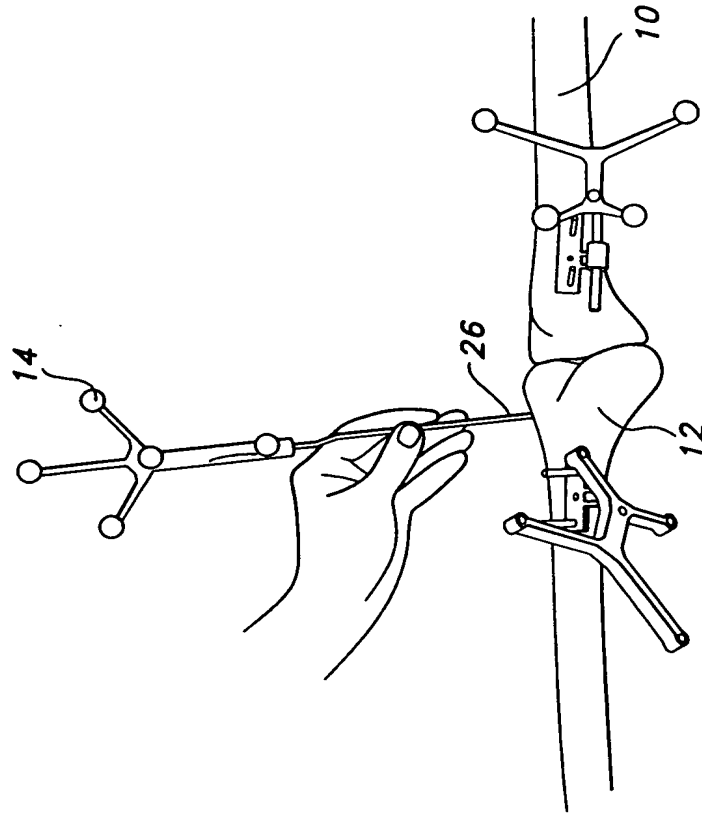
**FIG 13**

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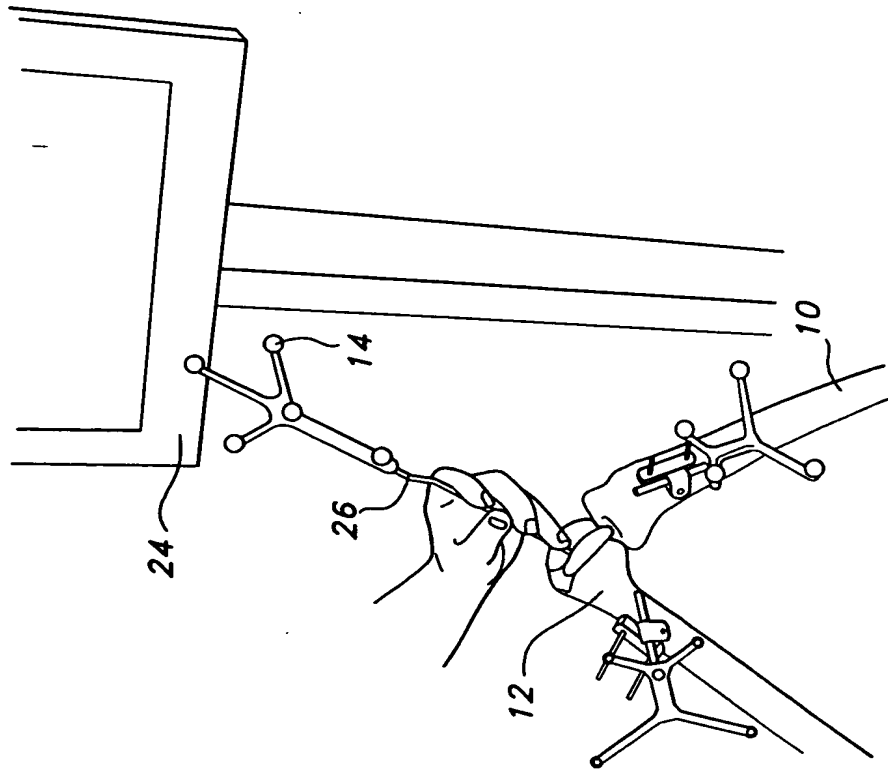
**FIG 14**

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**FIG. 15**

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**FIG 16**

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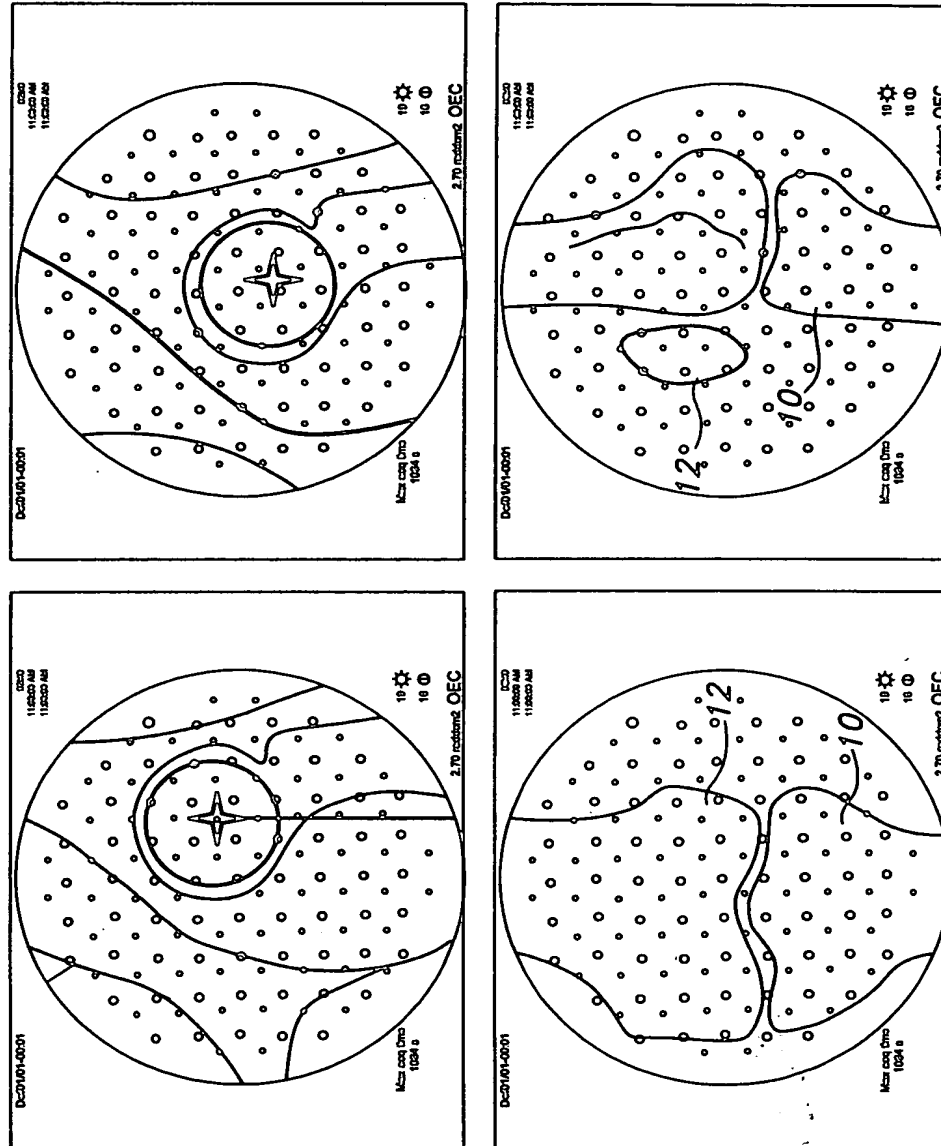


FIG 18

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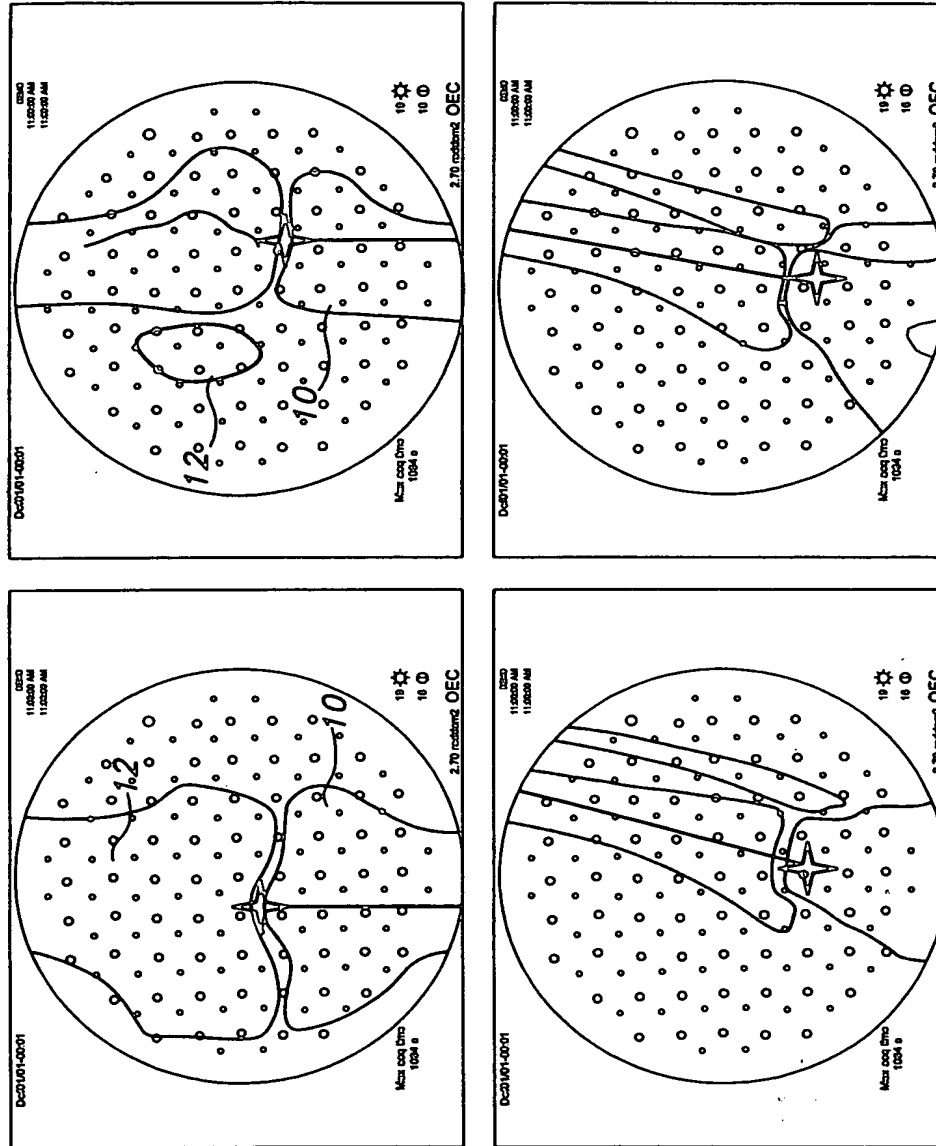
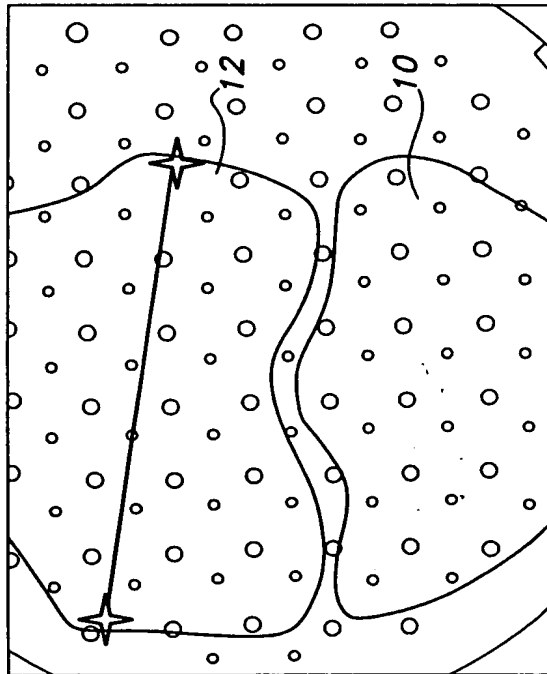
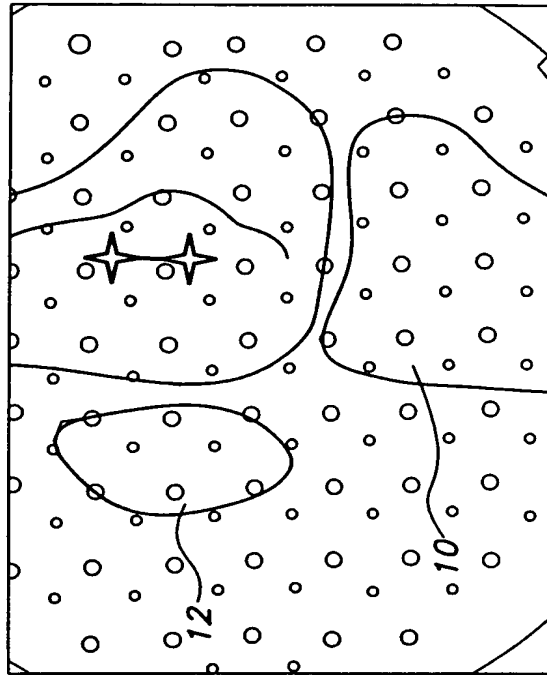


FIG 19

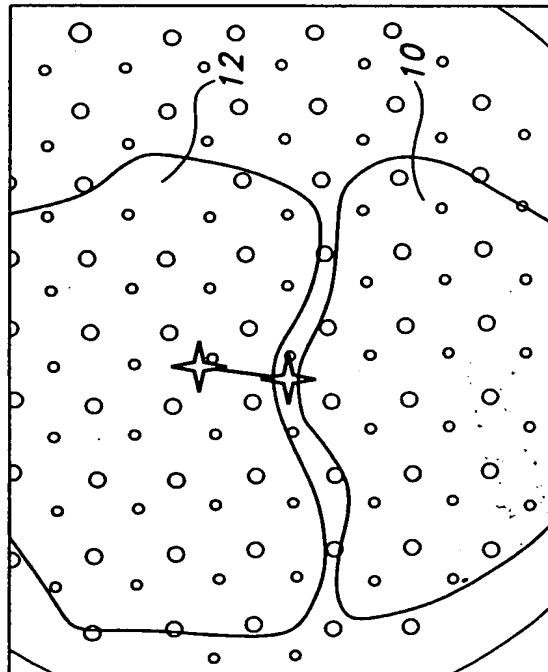
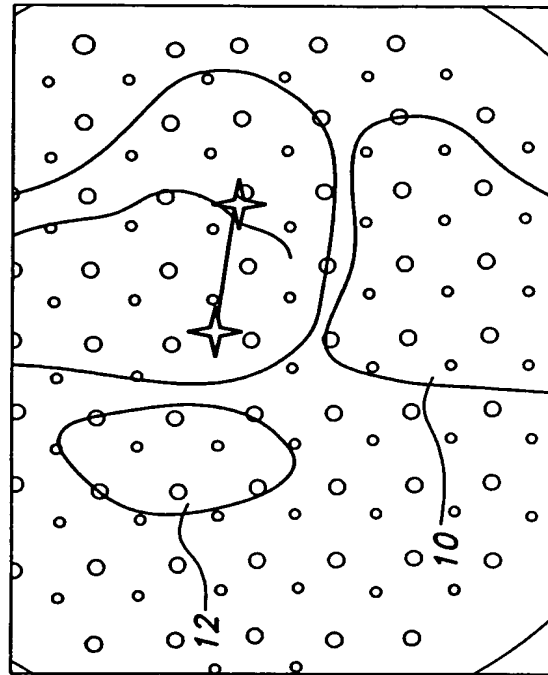


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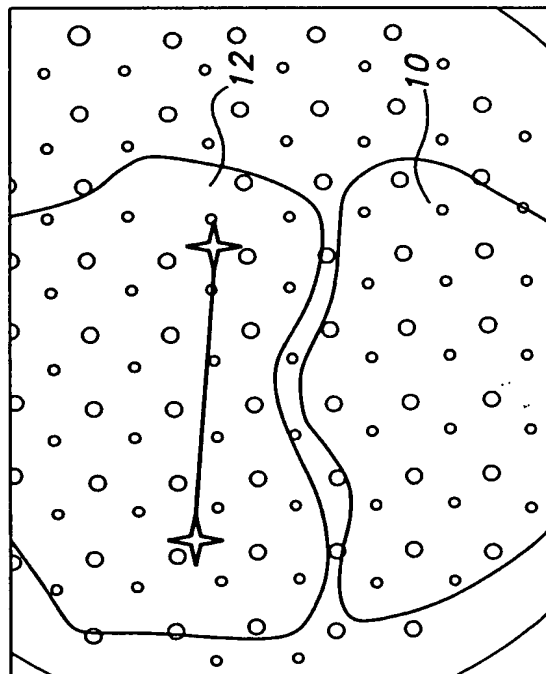
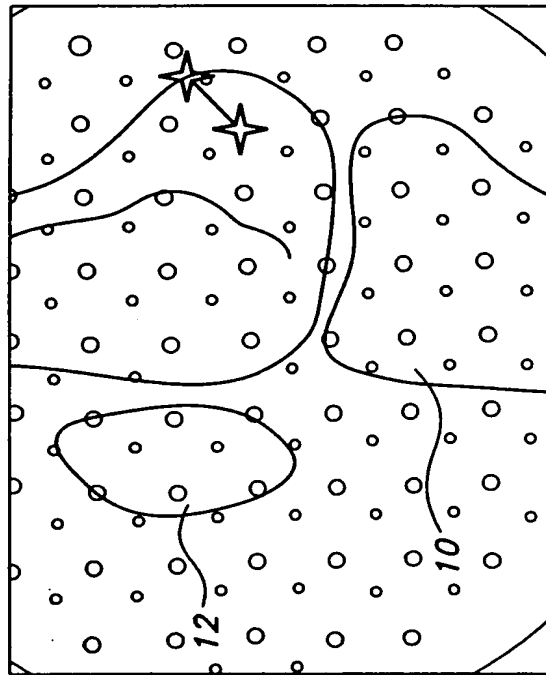
**FIG. 20**

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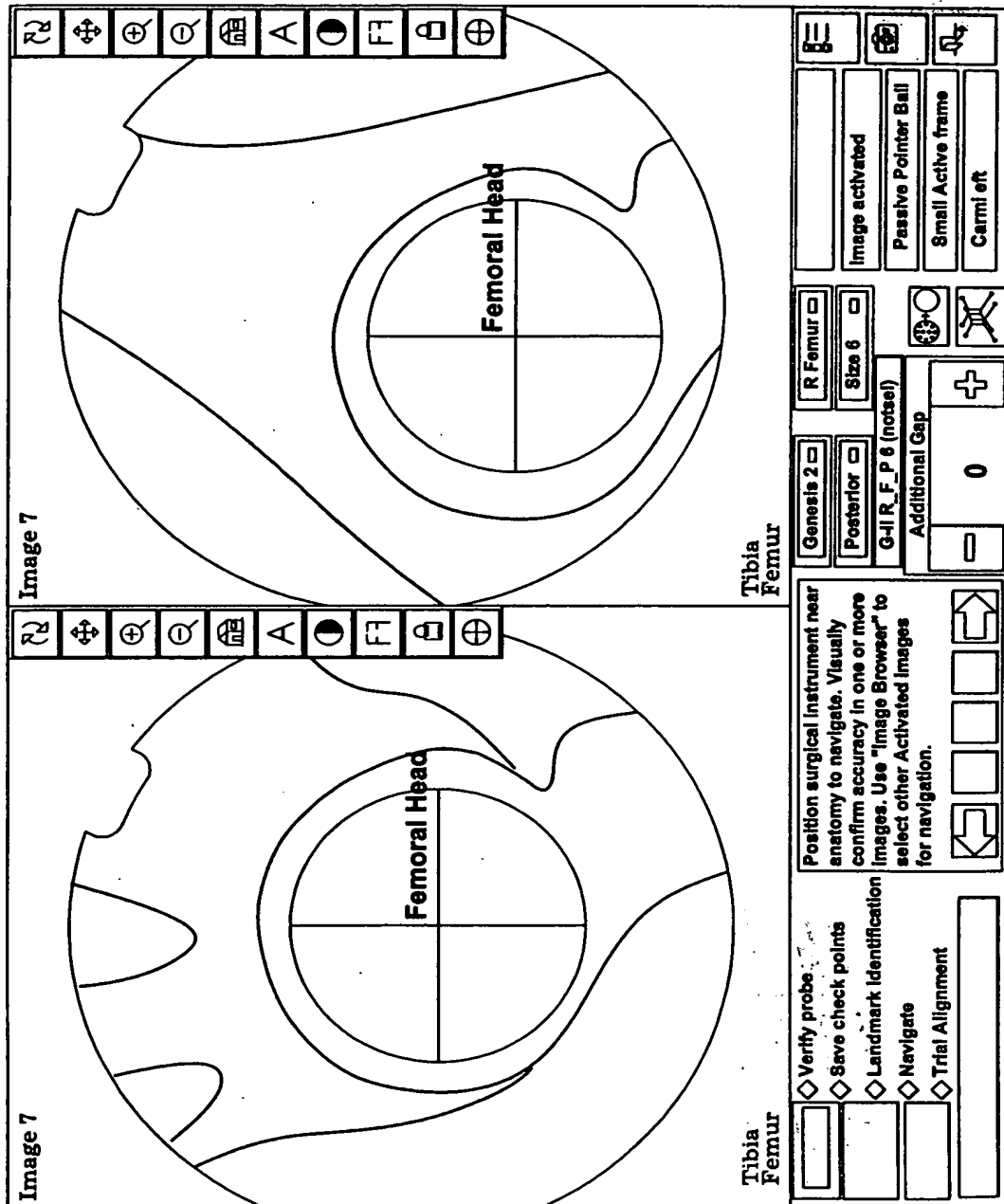
**FIG 21**

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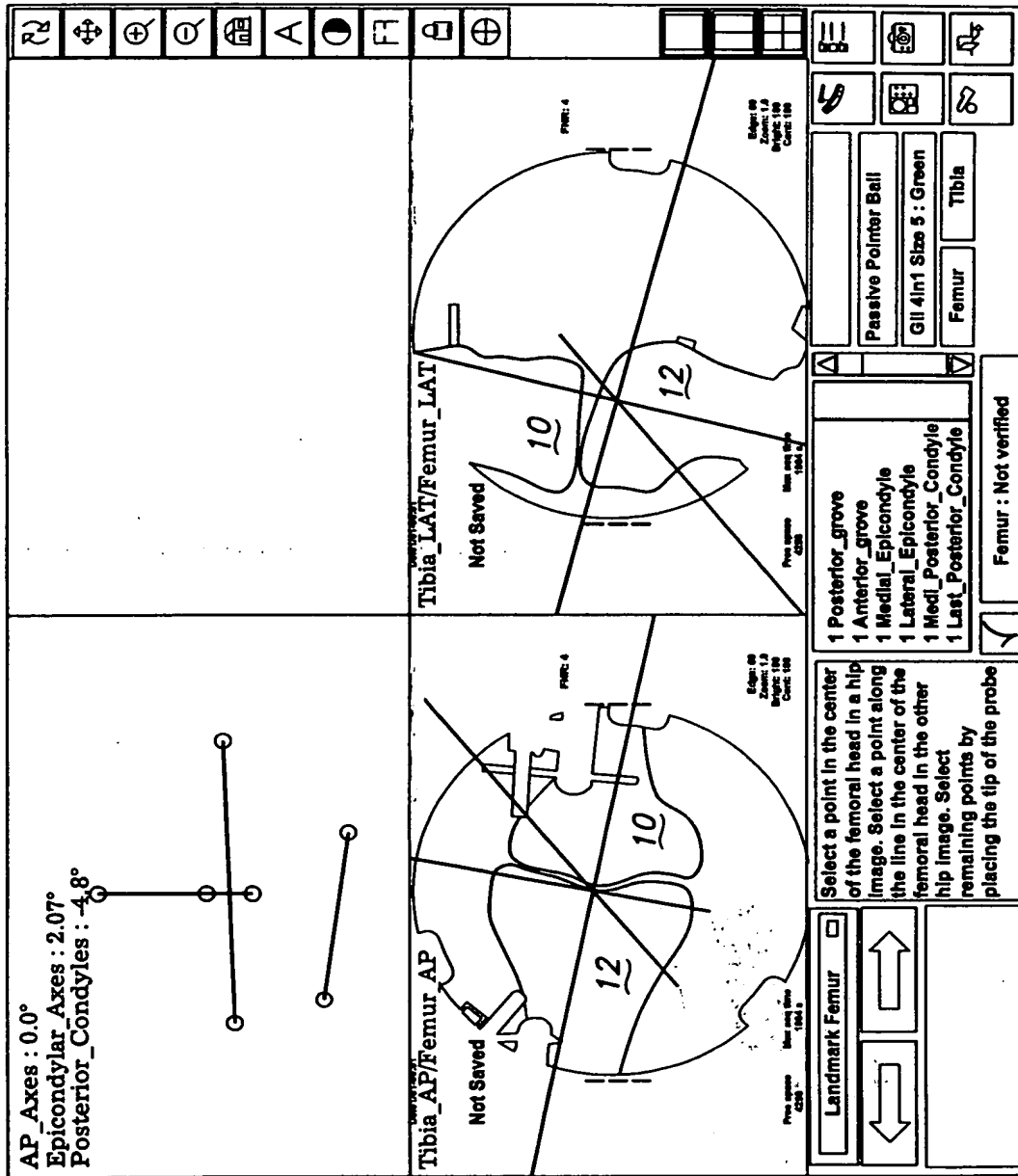
**FIG 22**

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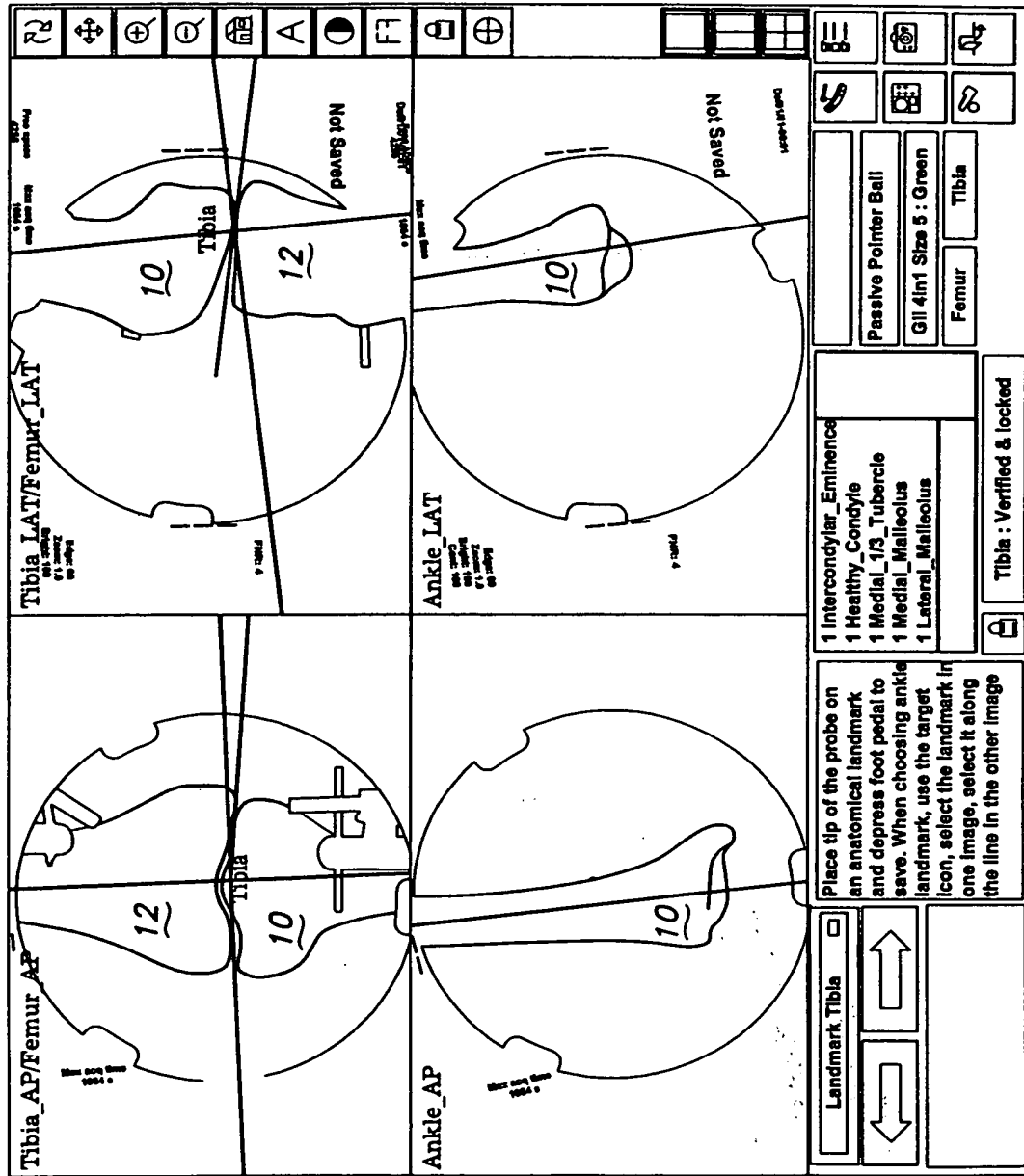
**FIG. 23**

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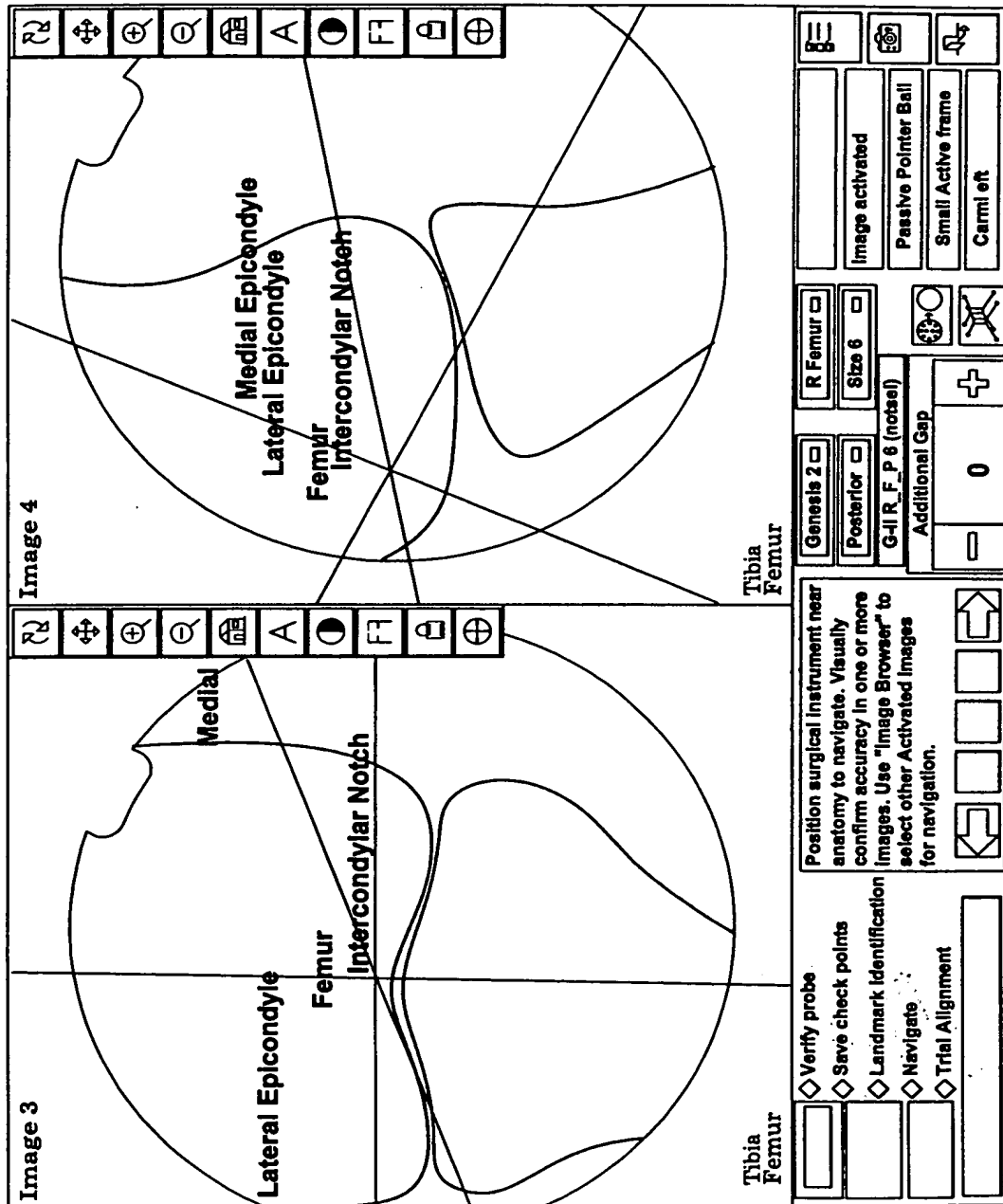
**FIG 24**

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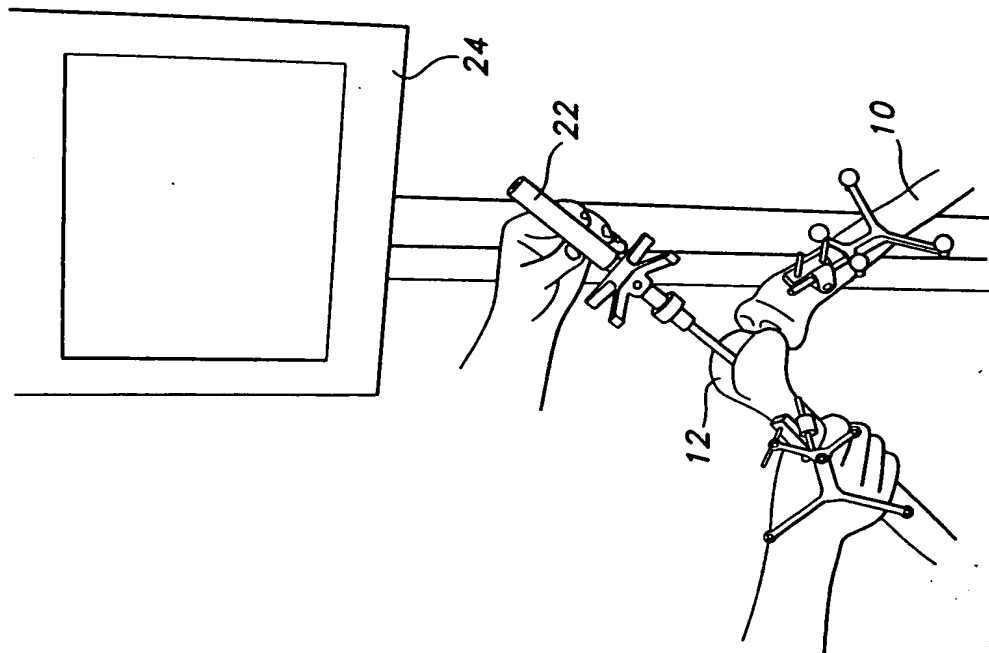
**FIG 25**

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**FIG 26**

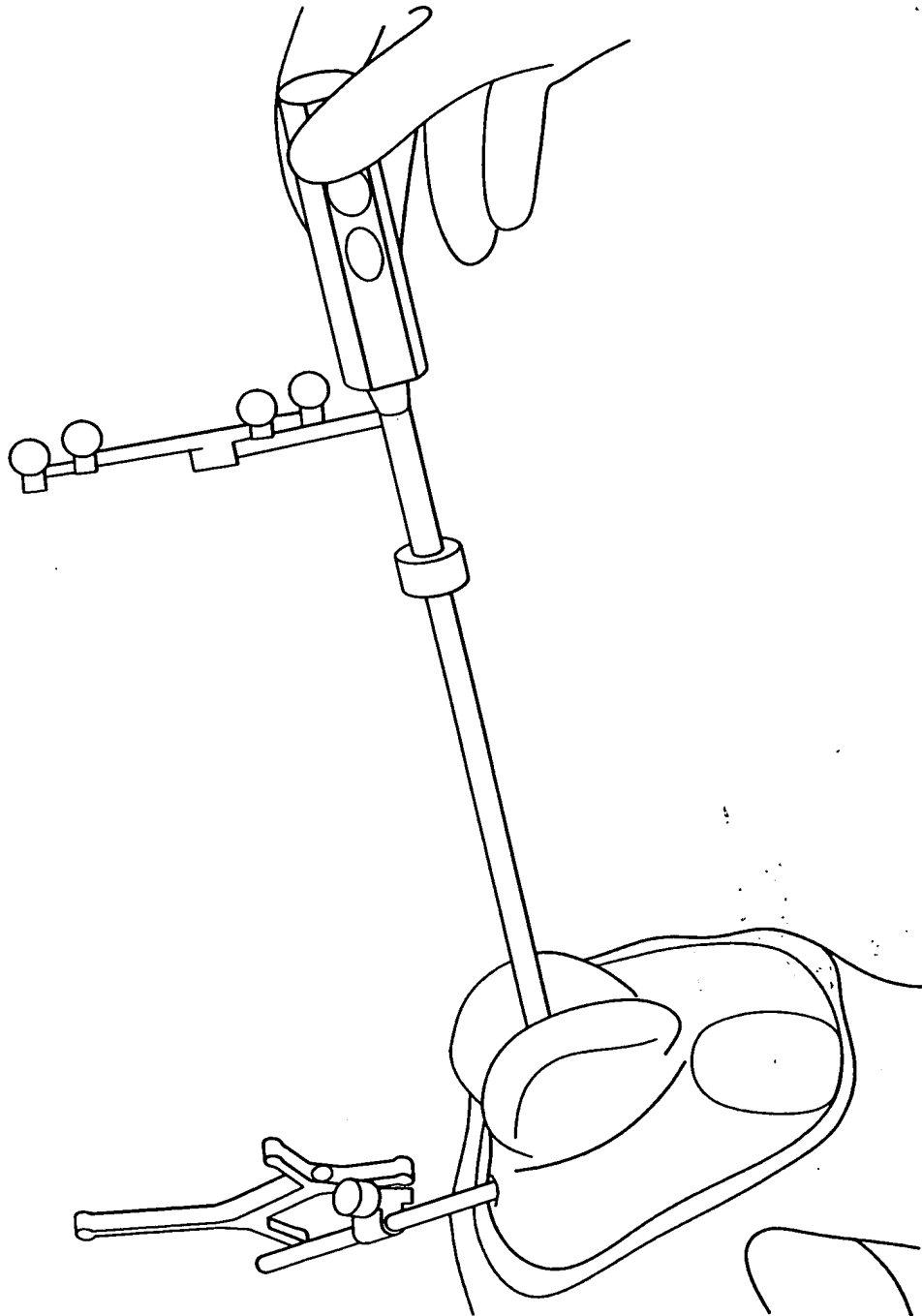
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**FIG 27**

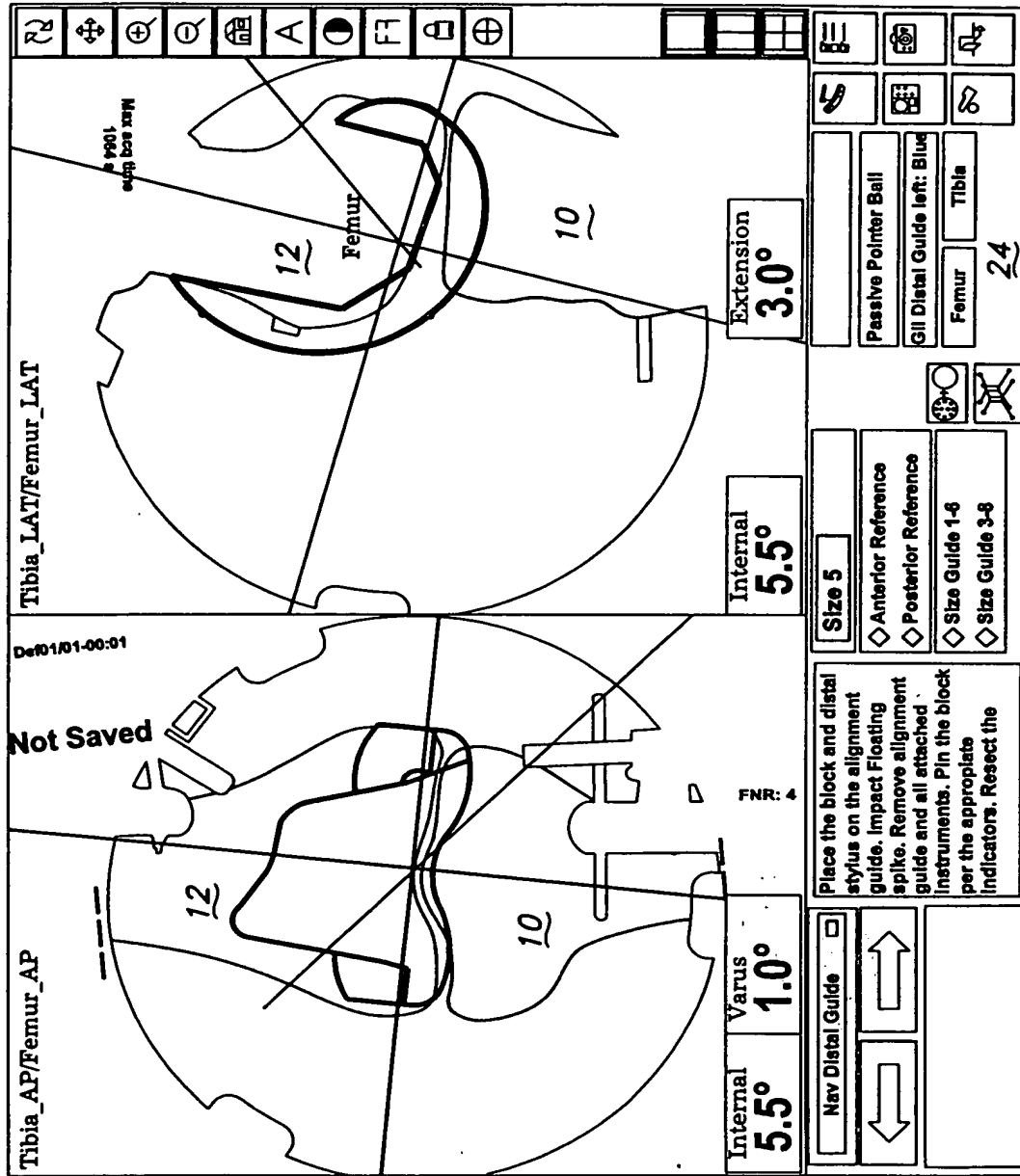


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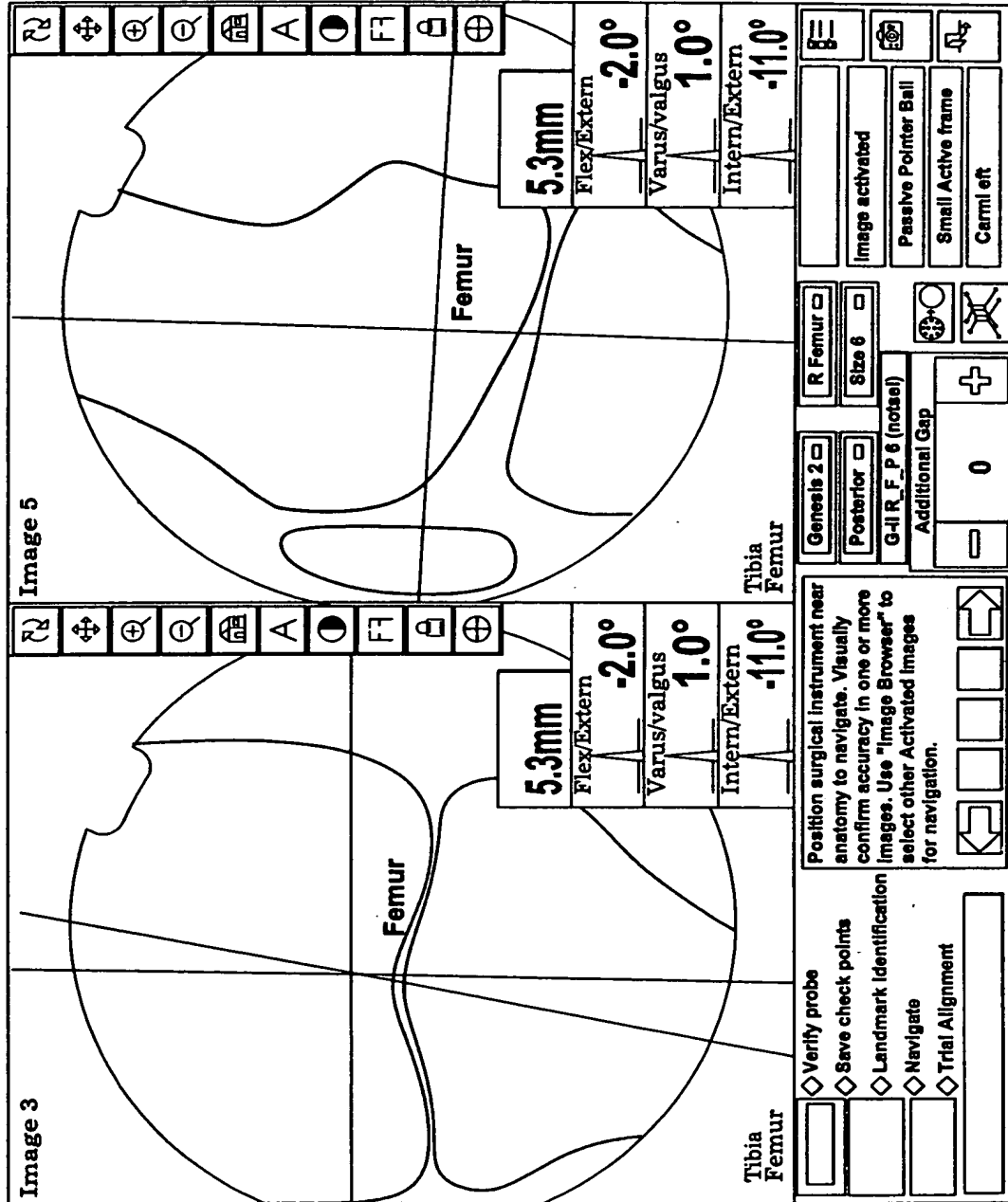


**FIG 28**

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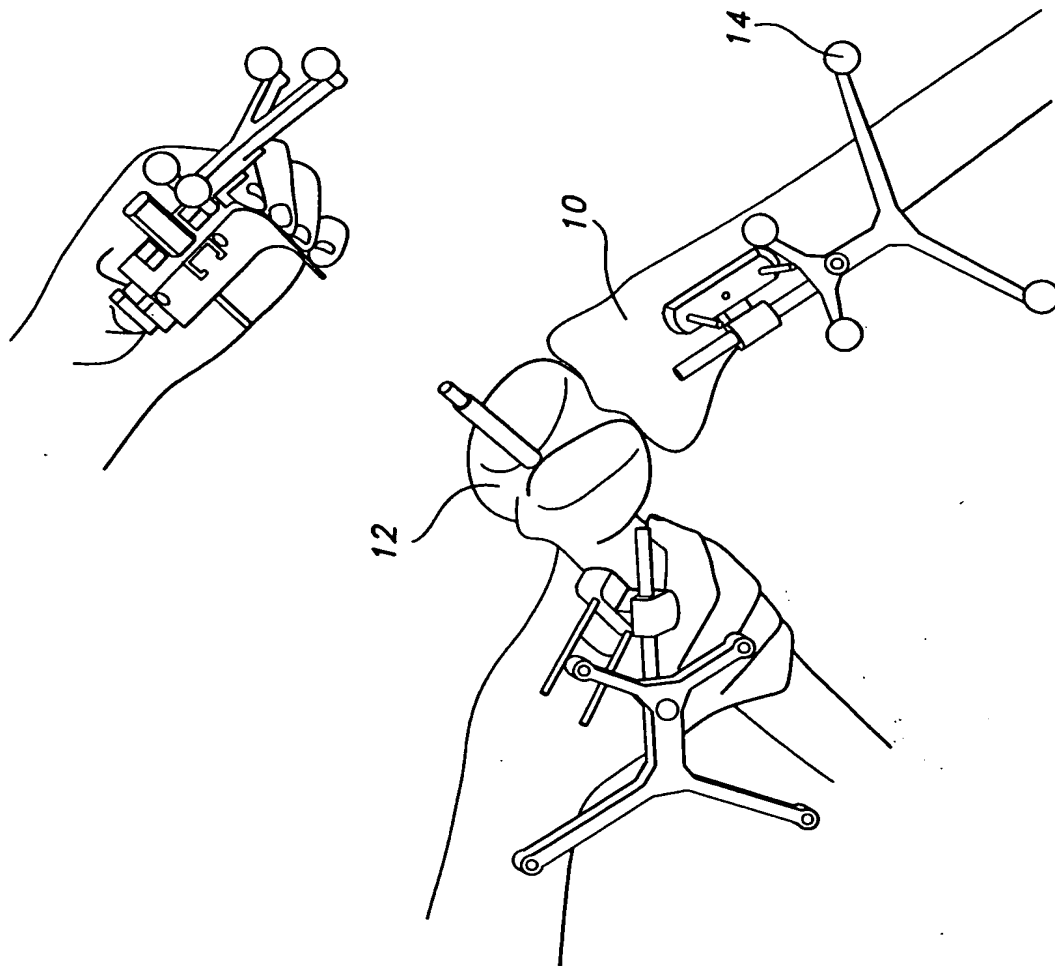


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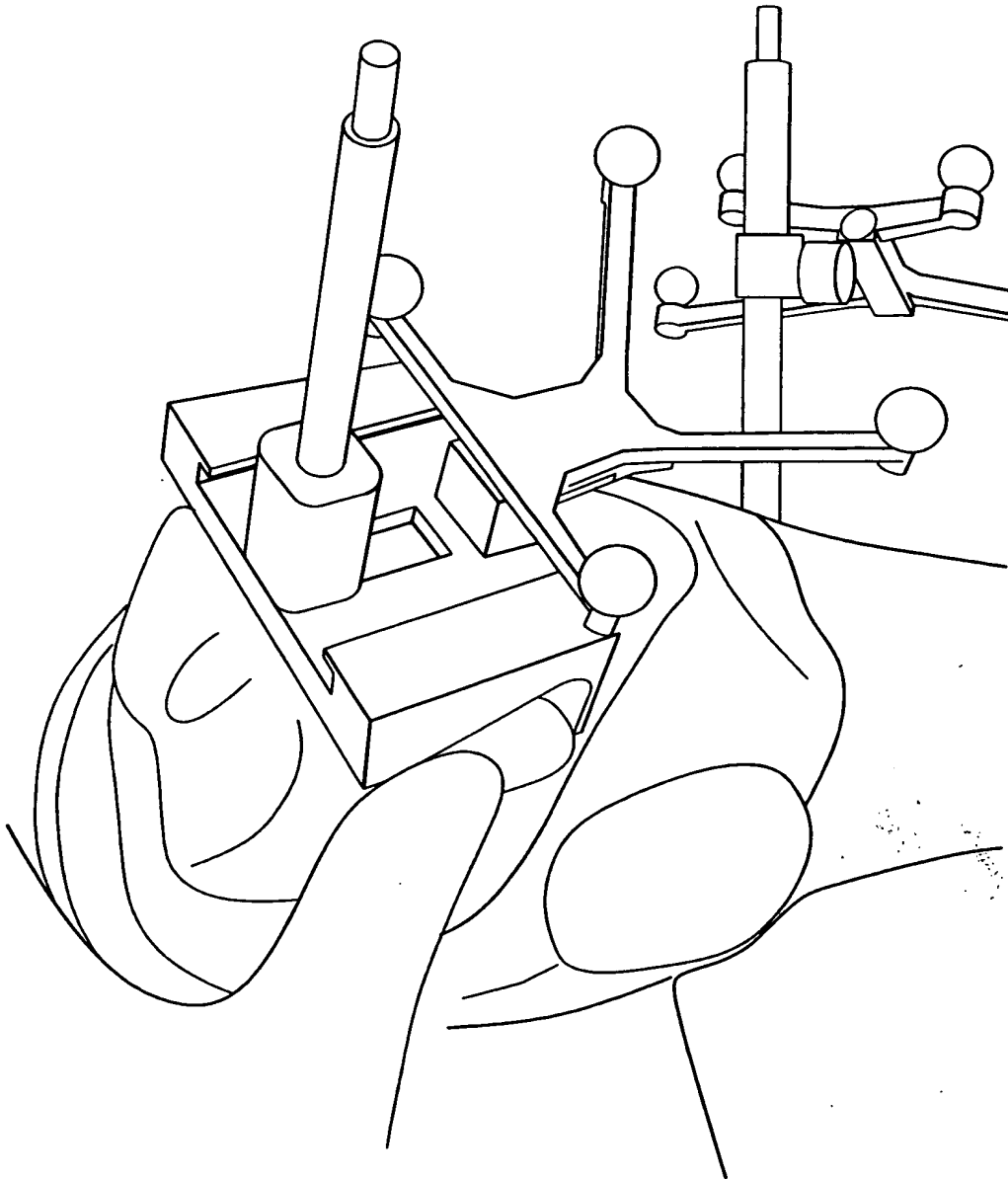
**FIG 30**

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**FIG 31**

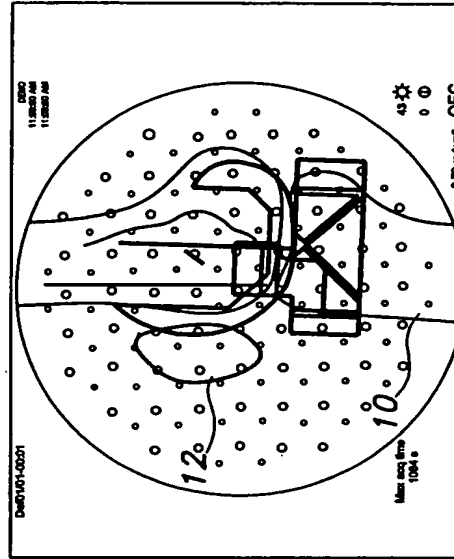
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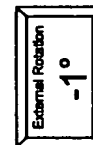
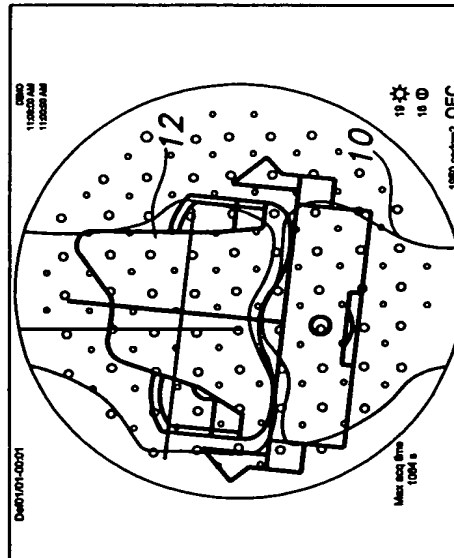
**FIG 32**

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3°



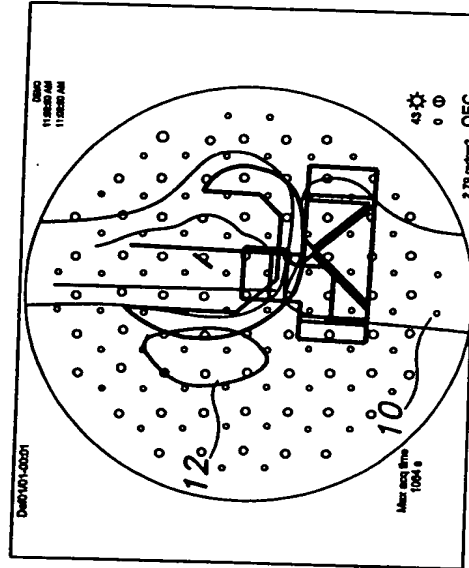
6°



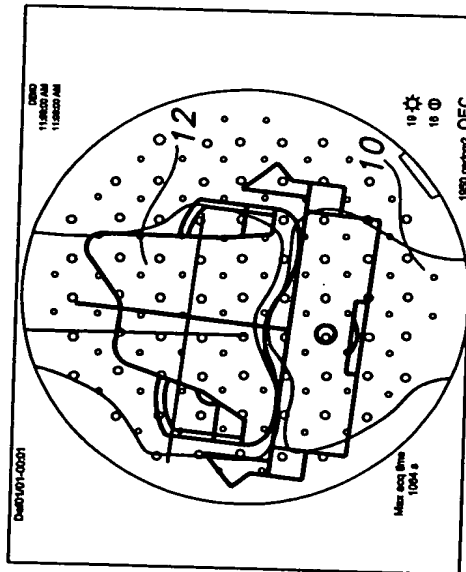
**FIG 33**

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3°



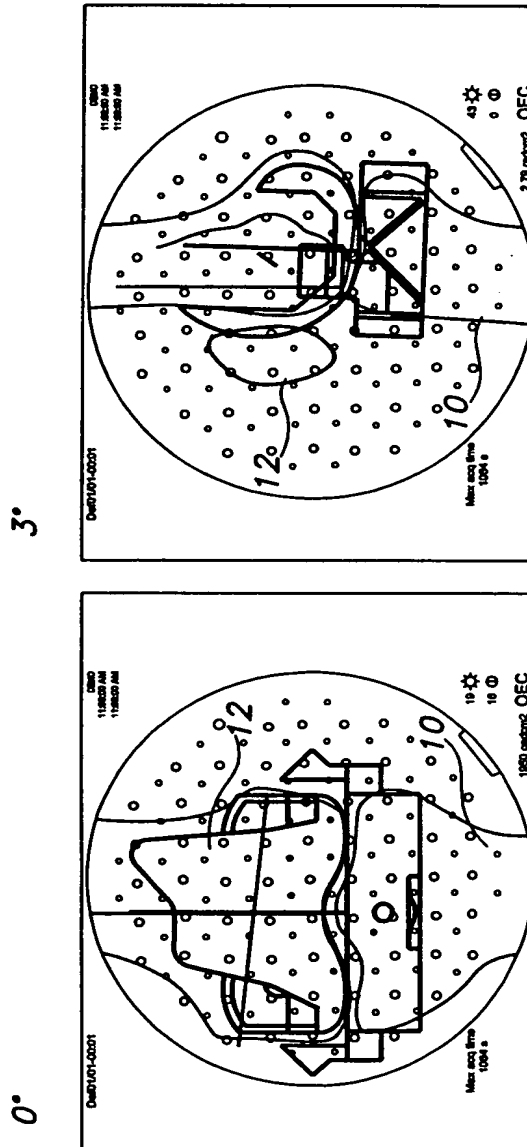
6°



External Rotation  
 3°

**FIG 34**

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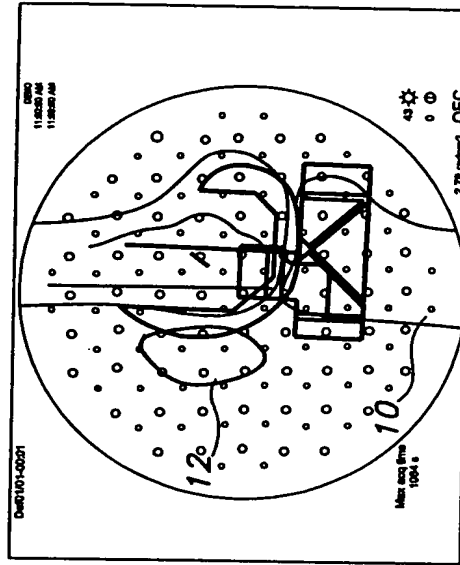
External Rotation  
 3°

**FIG 35**

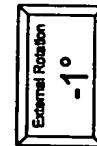
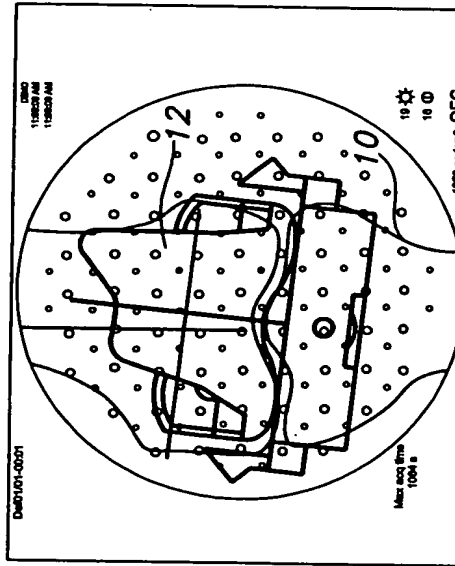


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3°

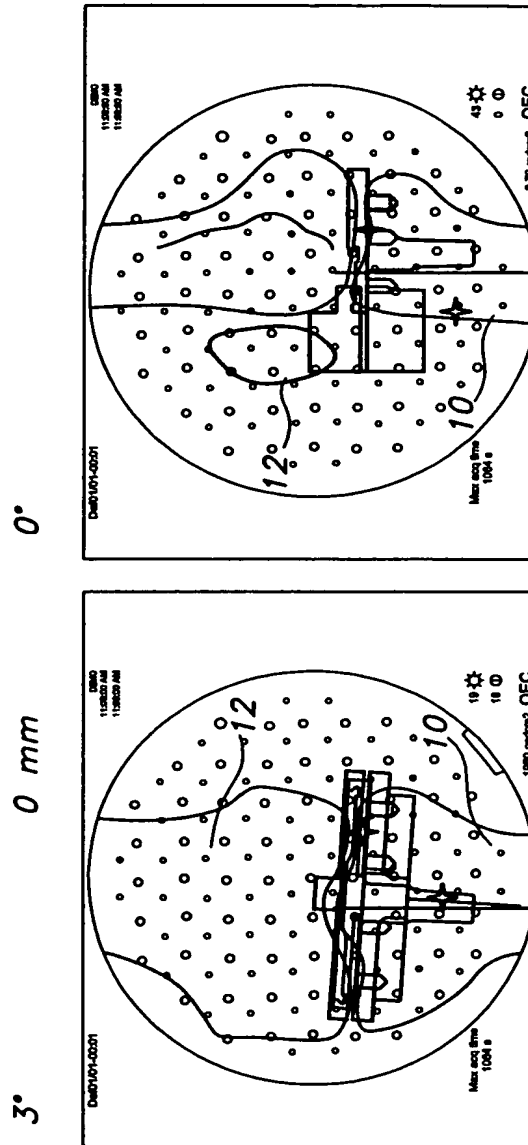


6°



**FIG 36**

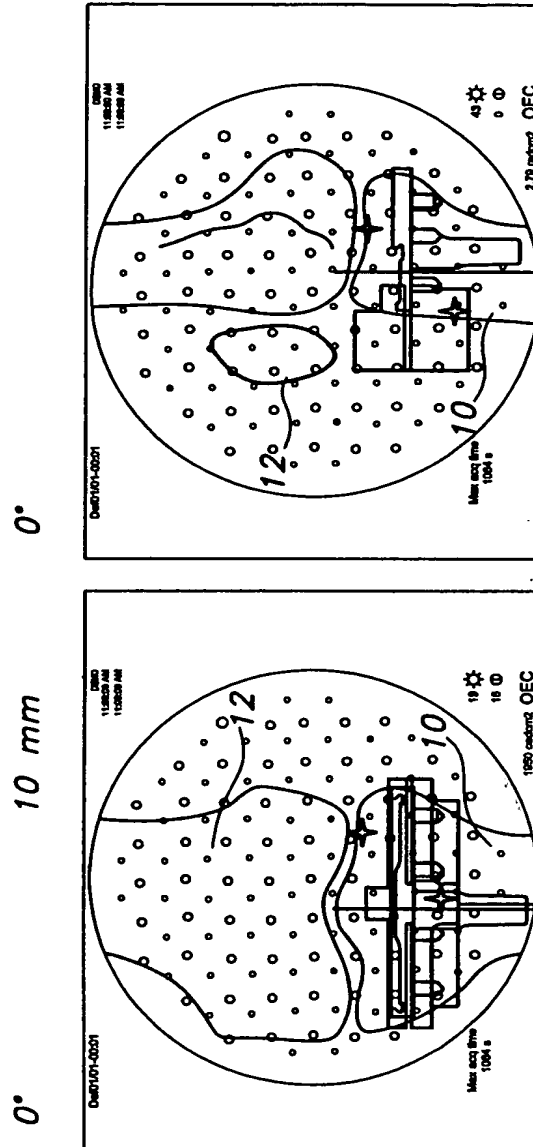
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External Rotation  
 6°

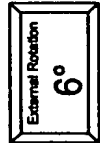
**FIG 37**

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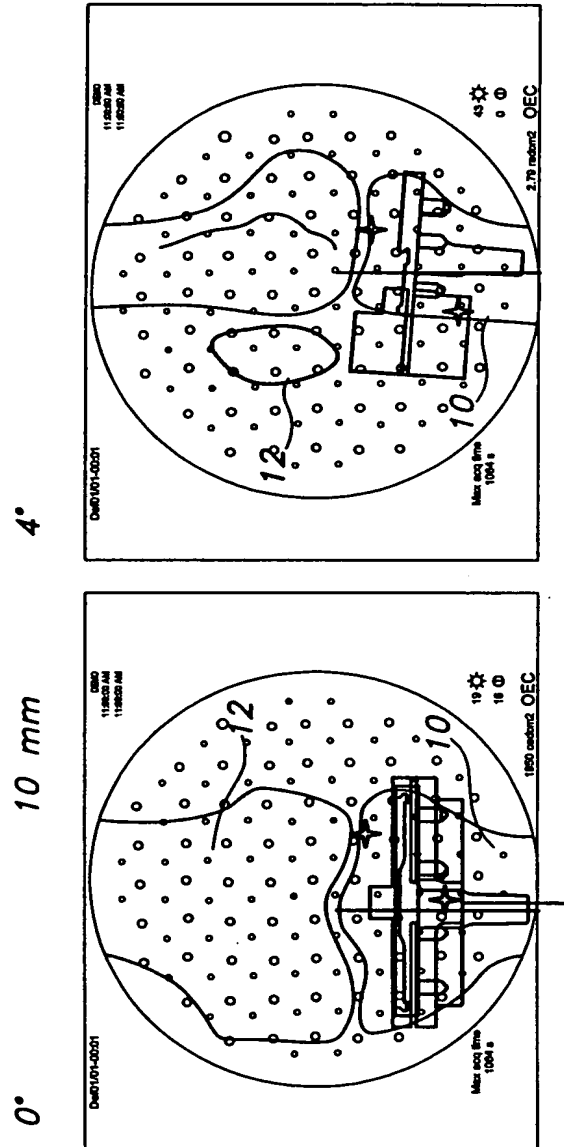
External Rotation  
 6°

FIG 38

$+$ 

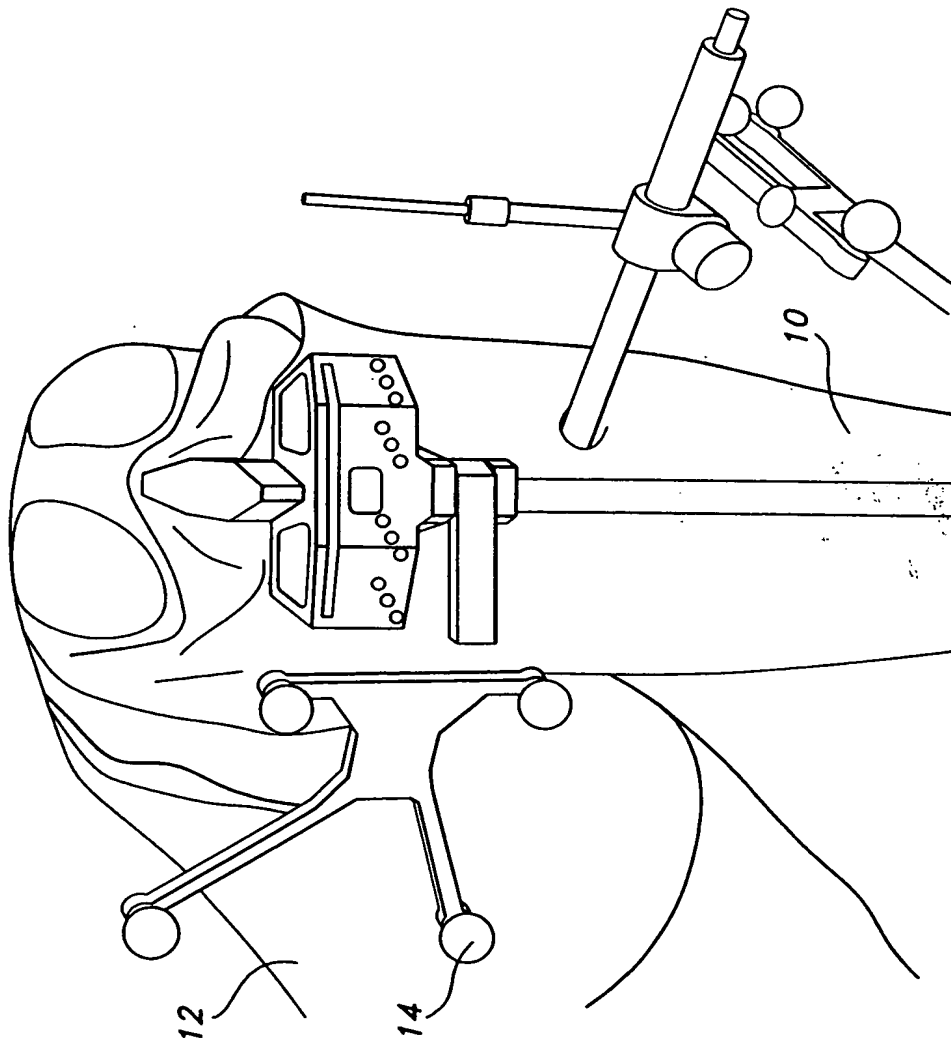
**FIG. 39**

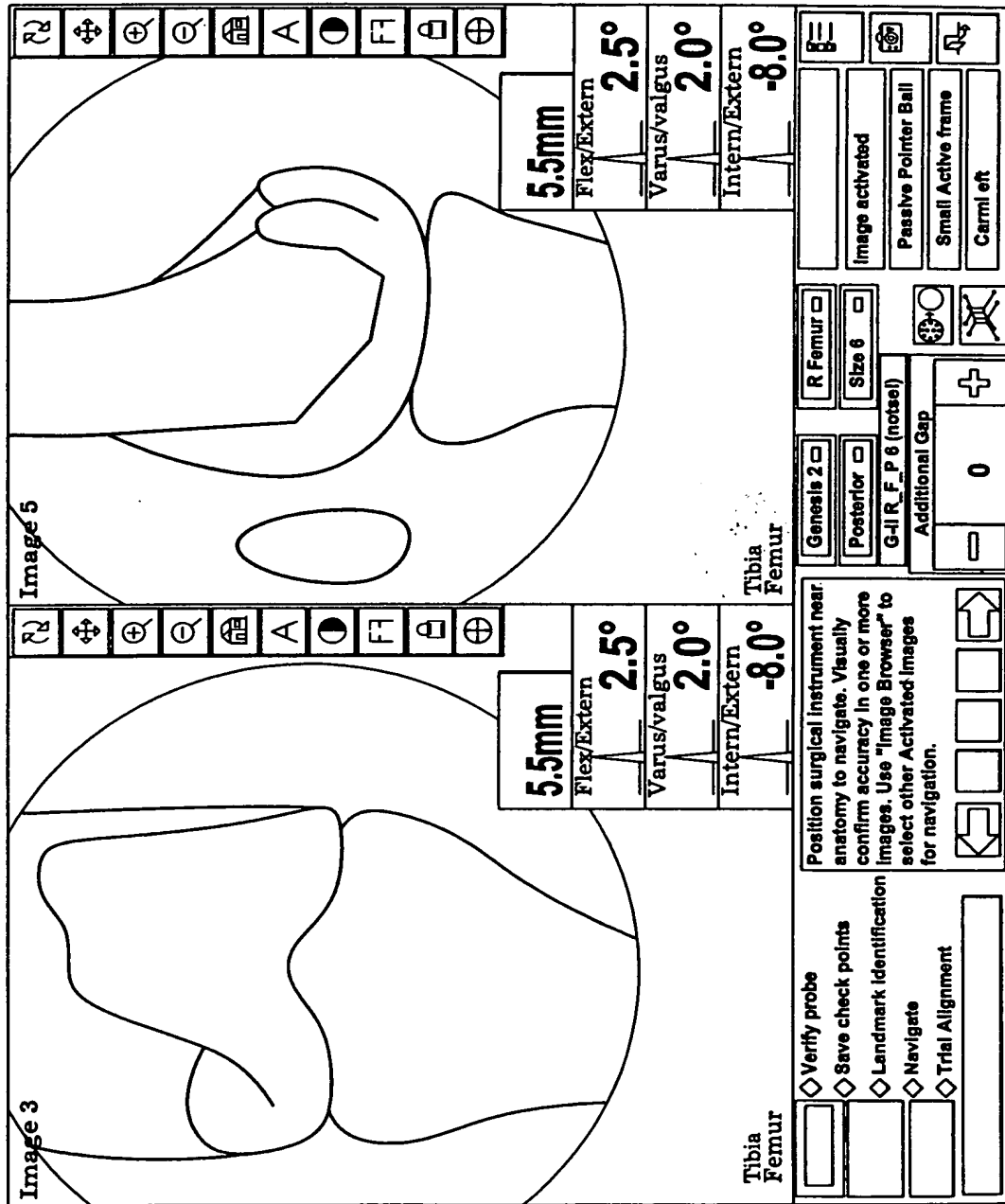
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**FIG 40**

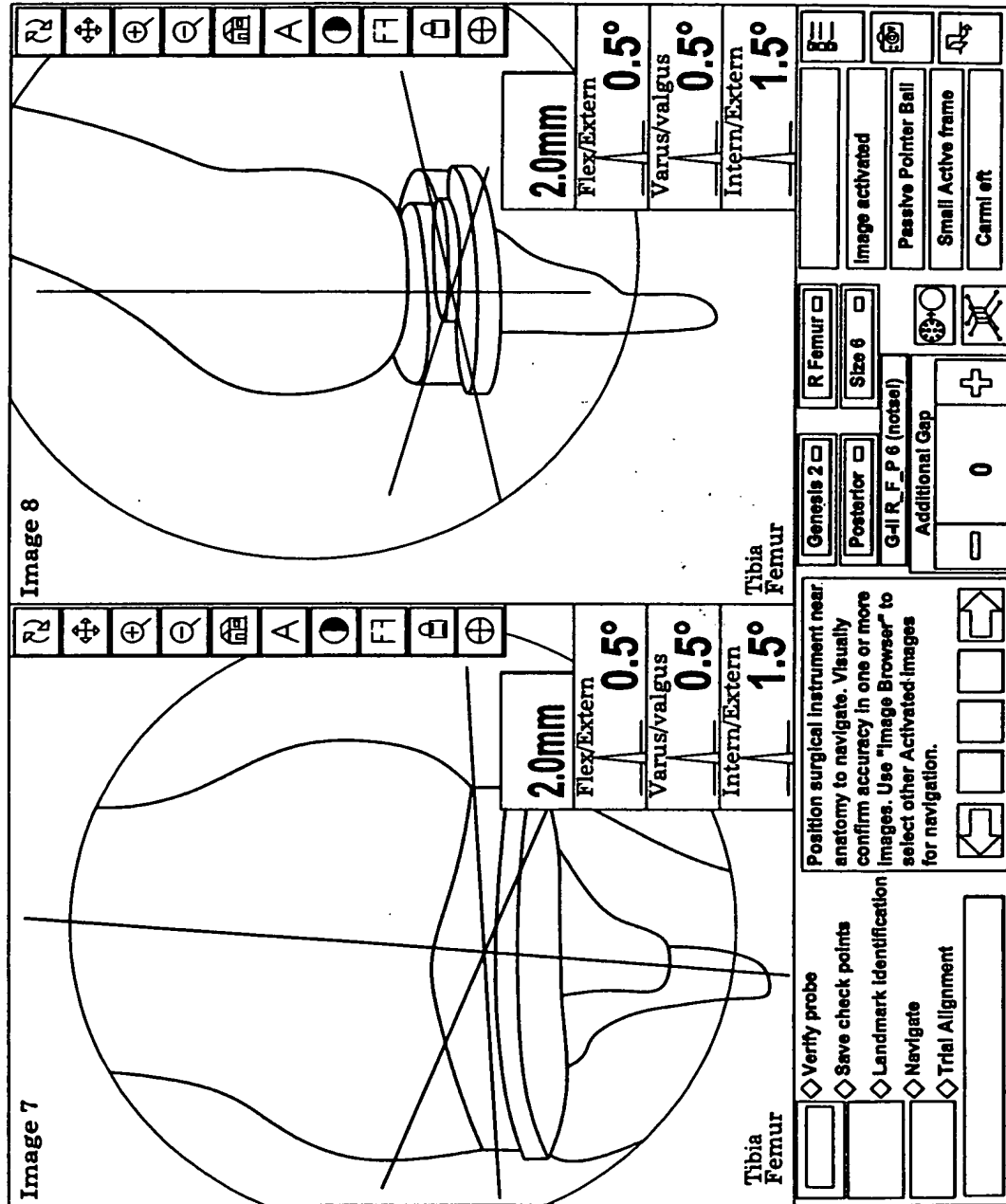
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**FIG. 42**

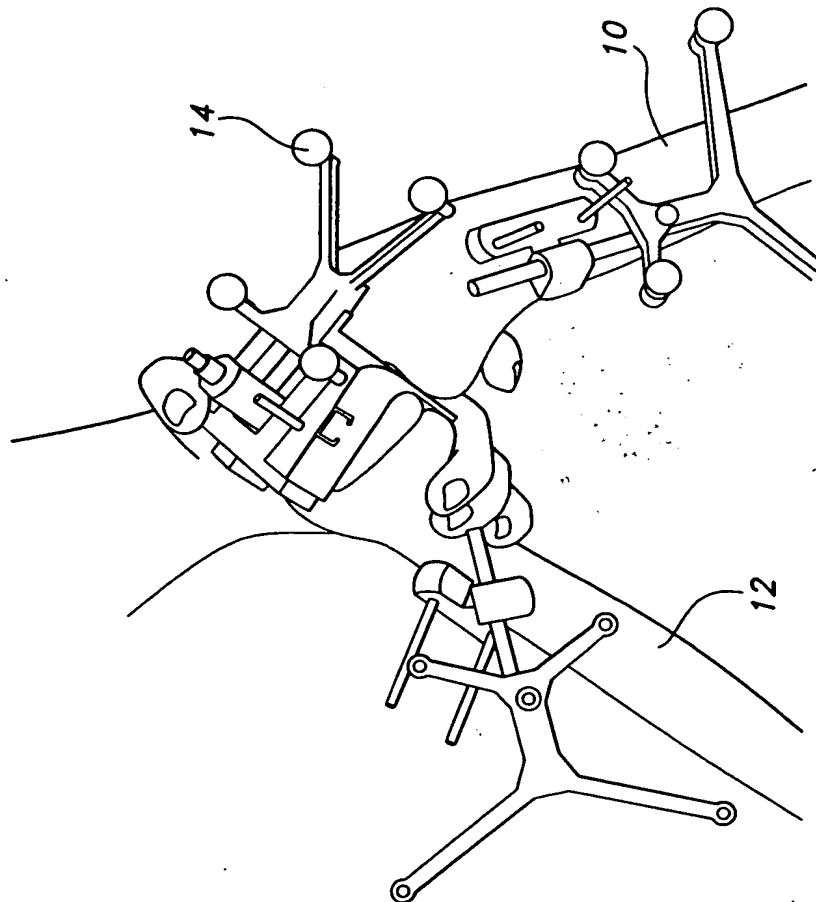
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**FIG 43**

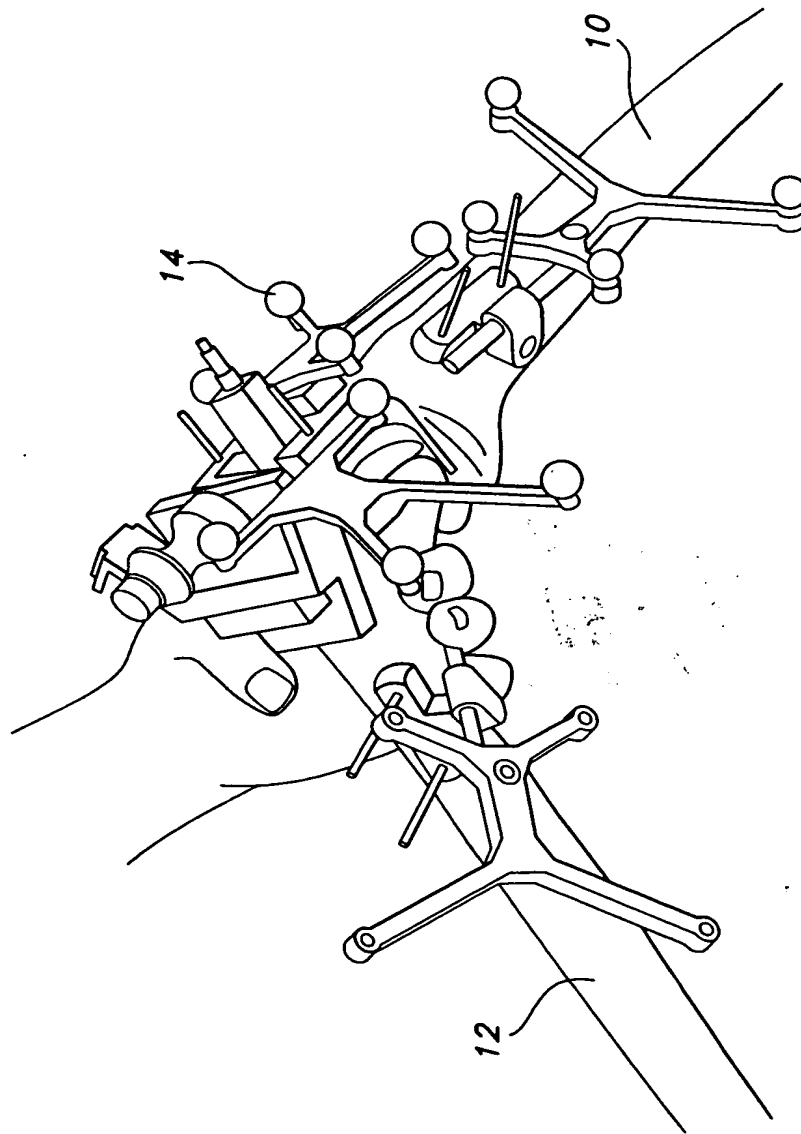


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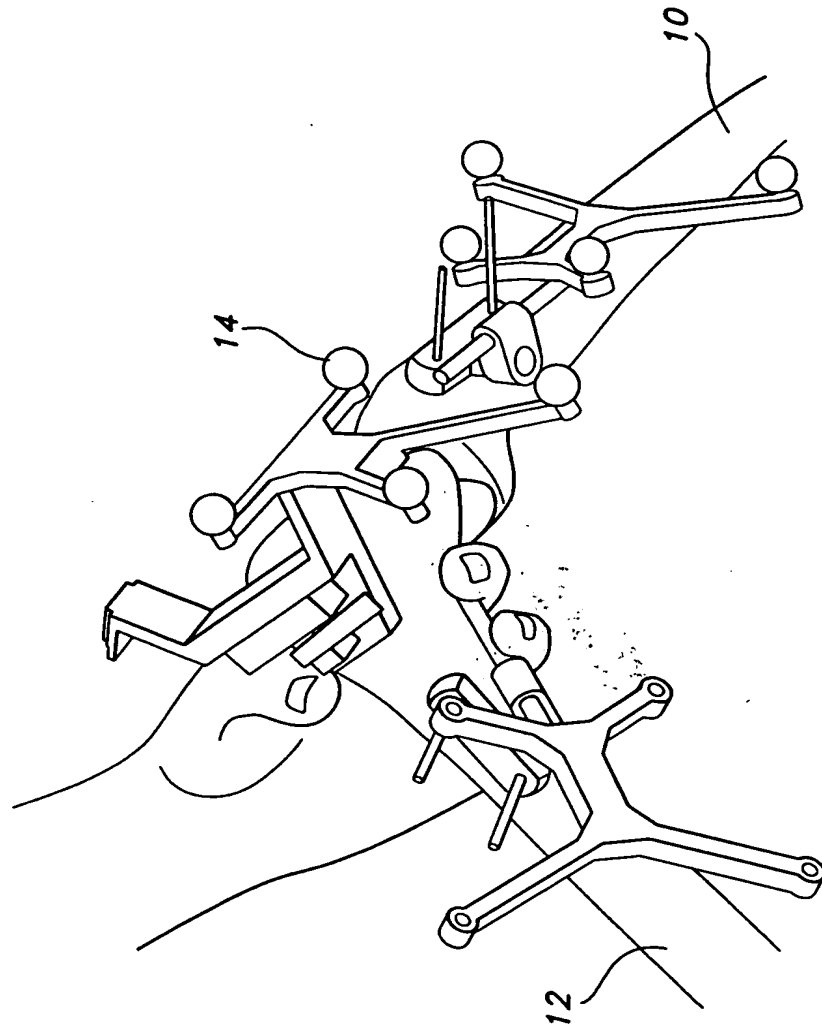


**FIG 44**

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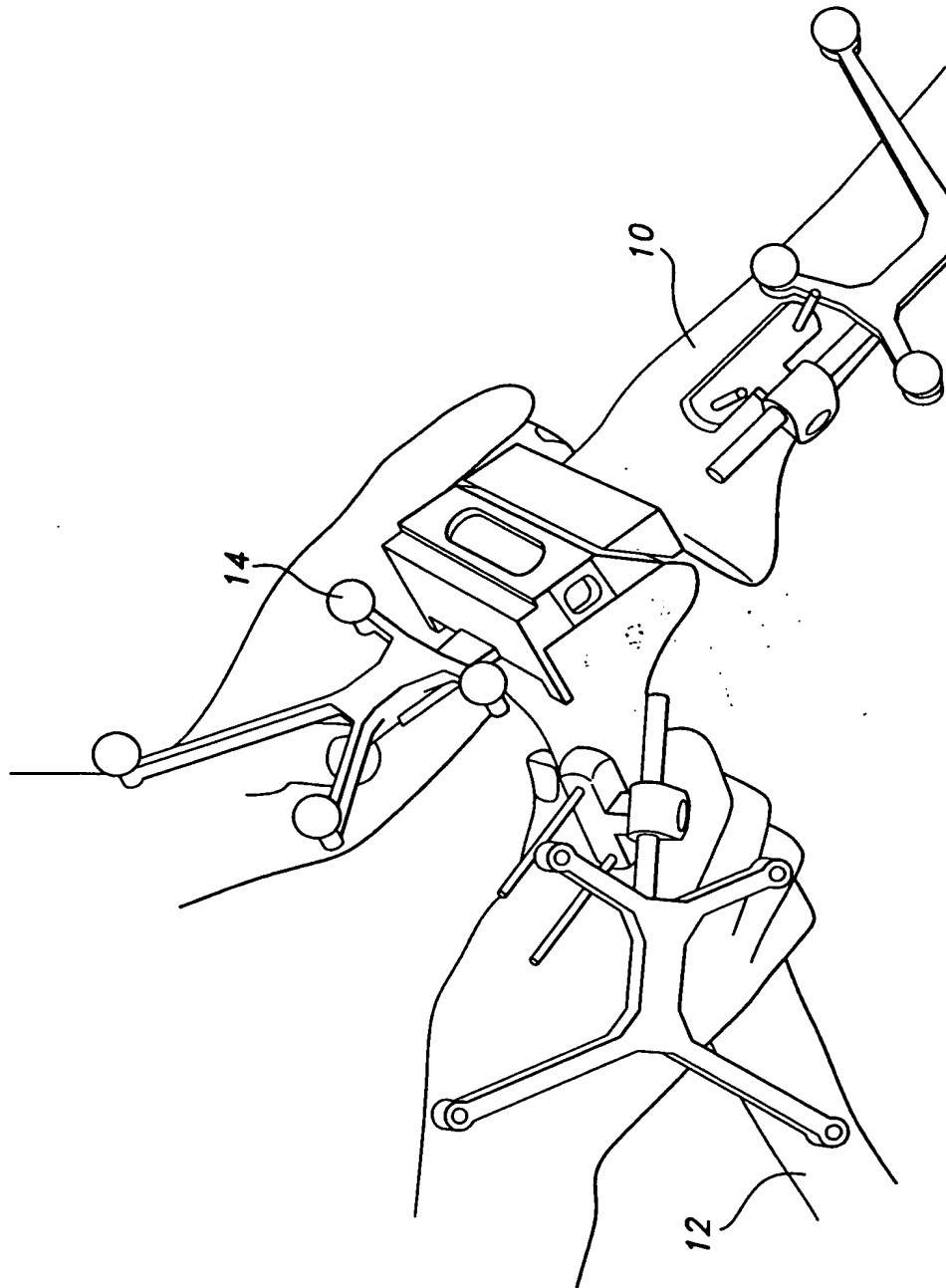


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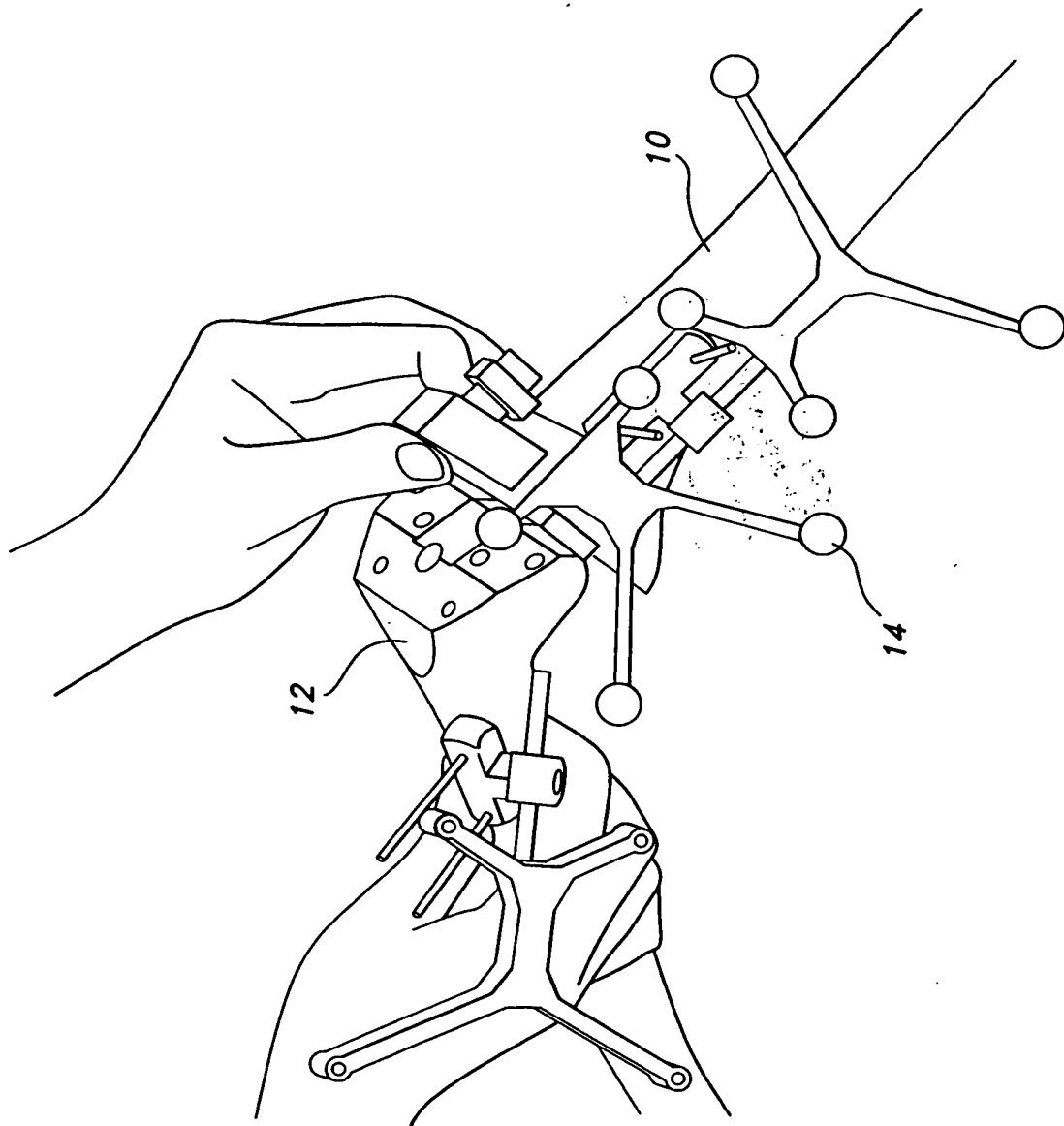


**FIG 46**

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**FIG 48**

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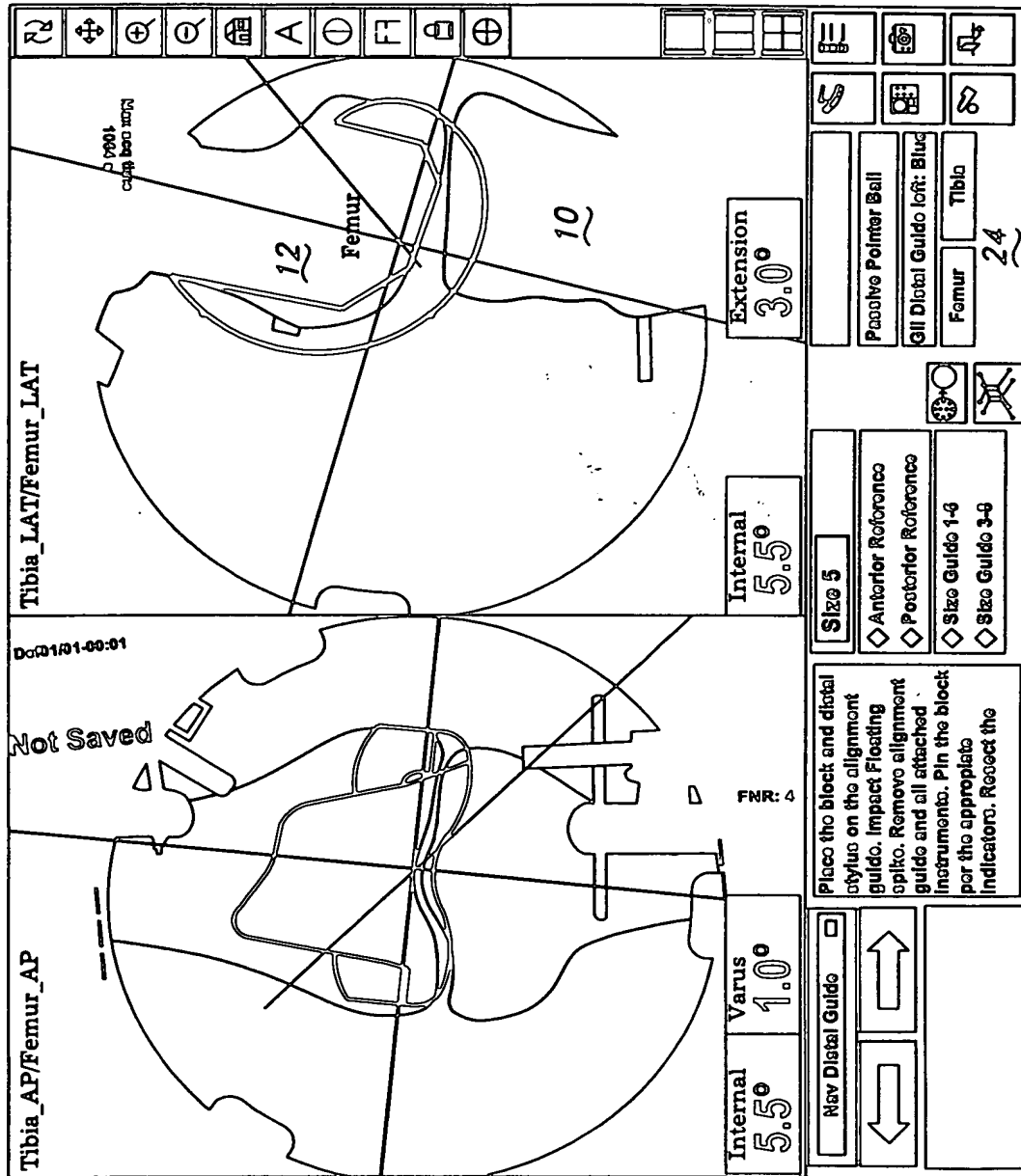
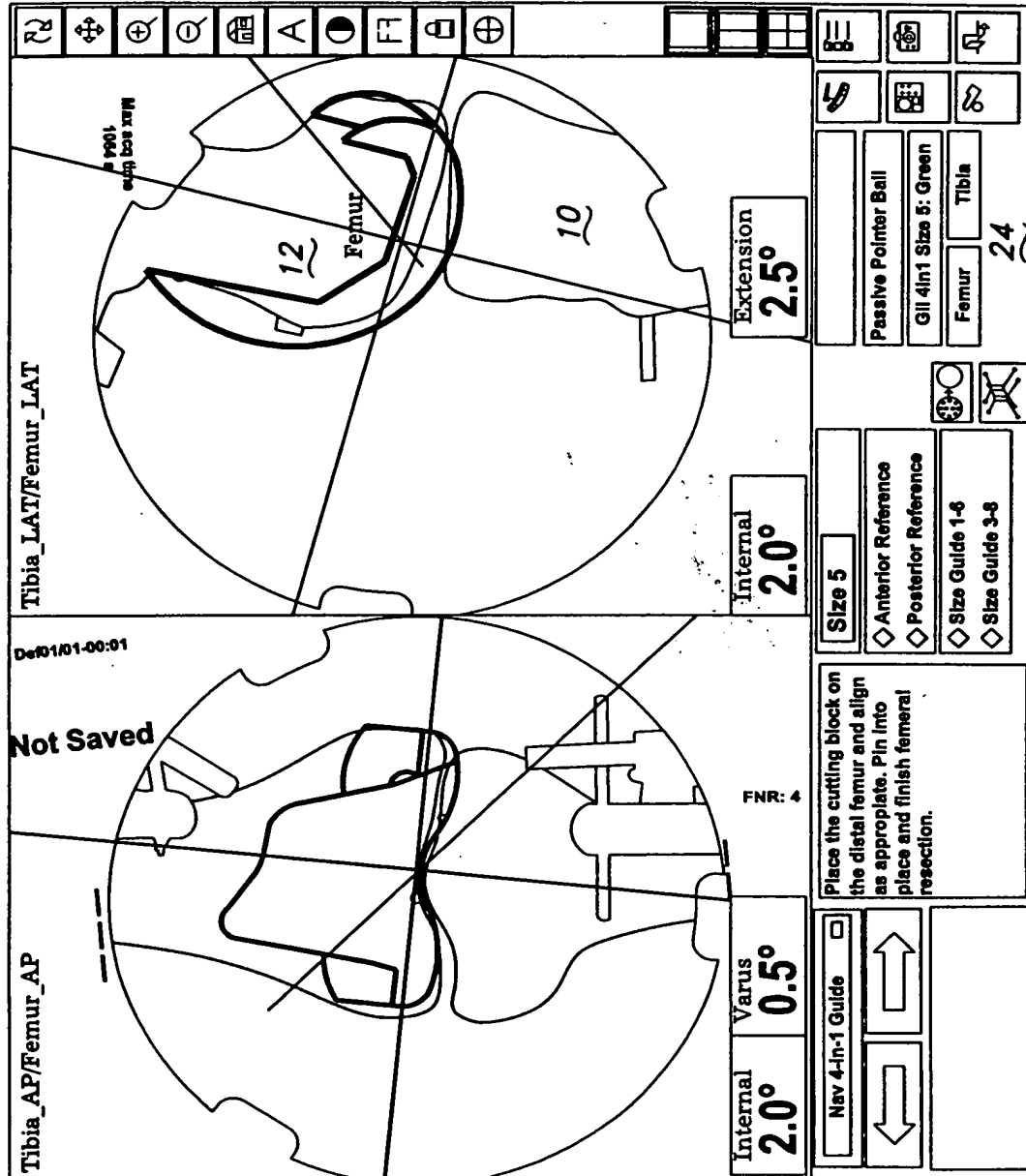


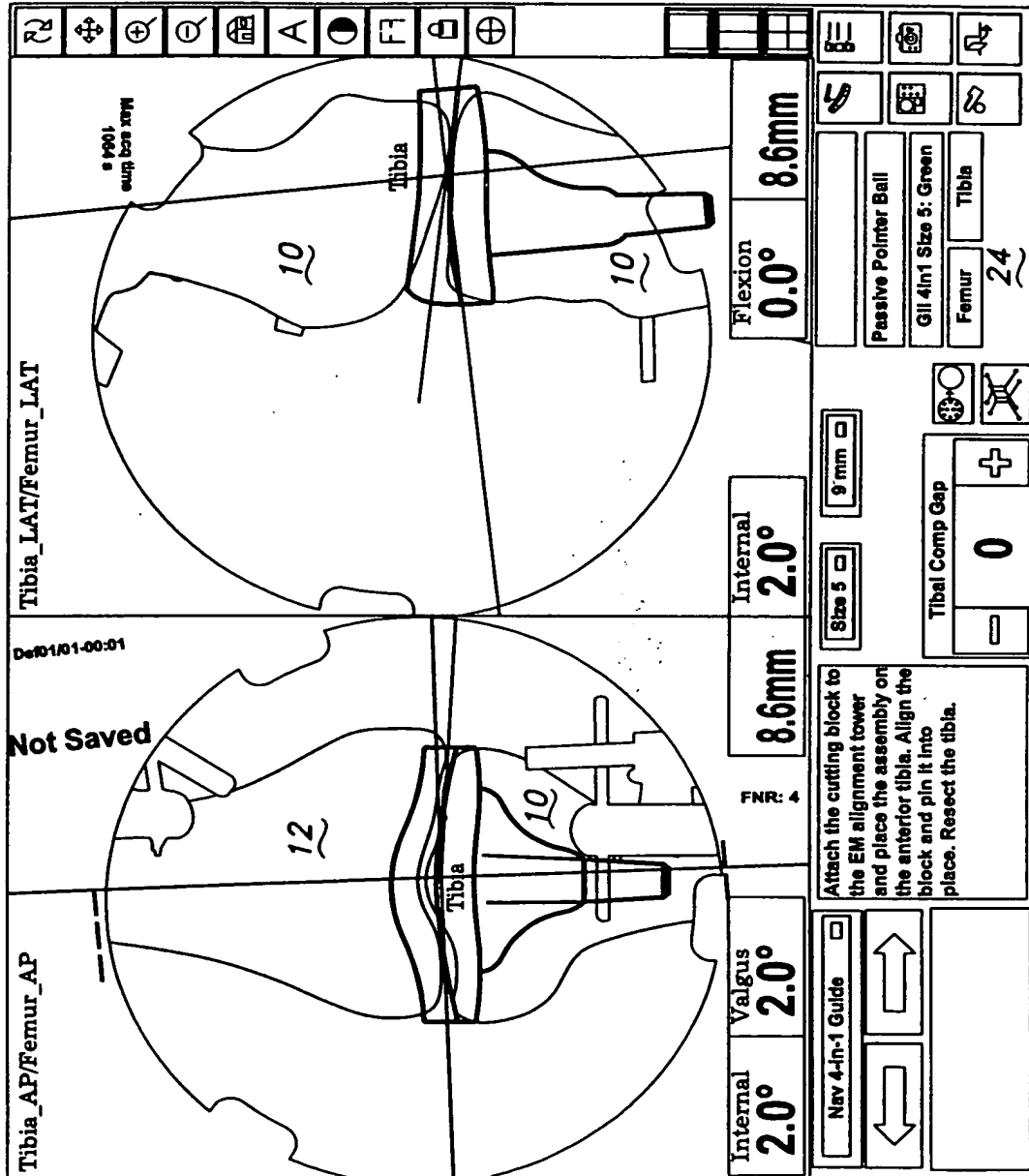
FIG 49

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**FIG 50**

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**FIG 51**



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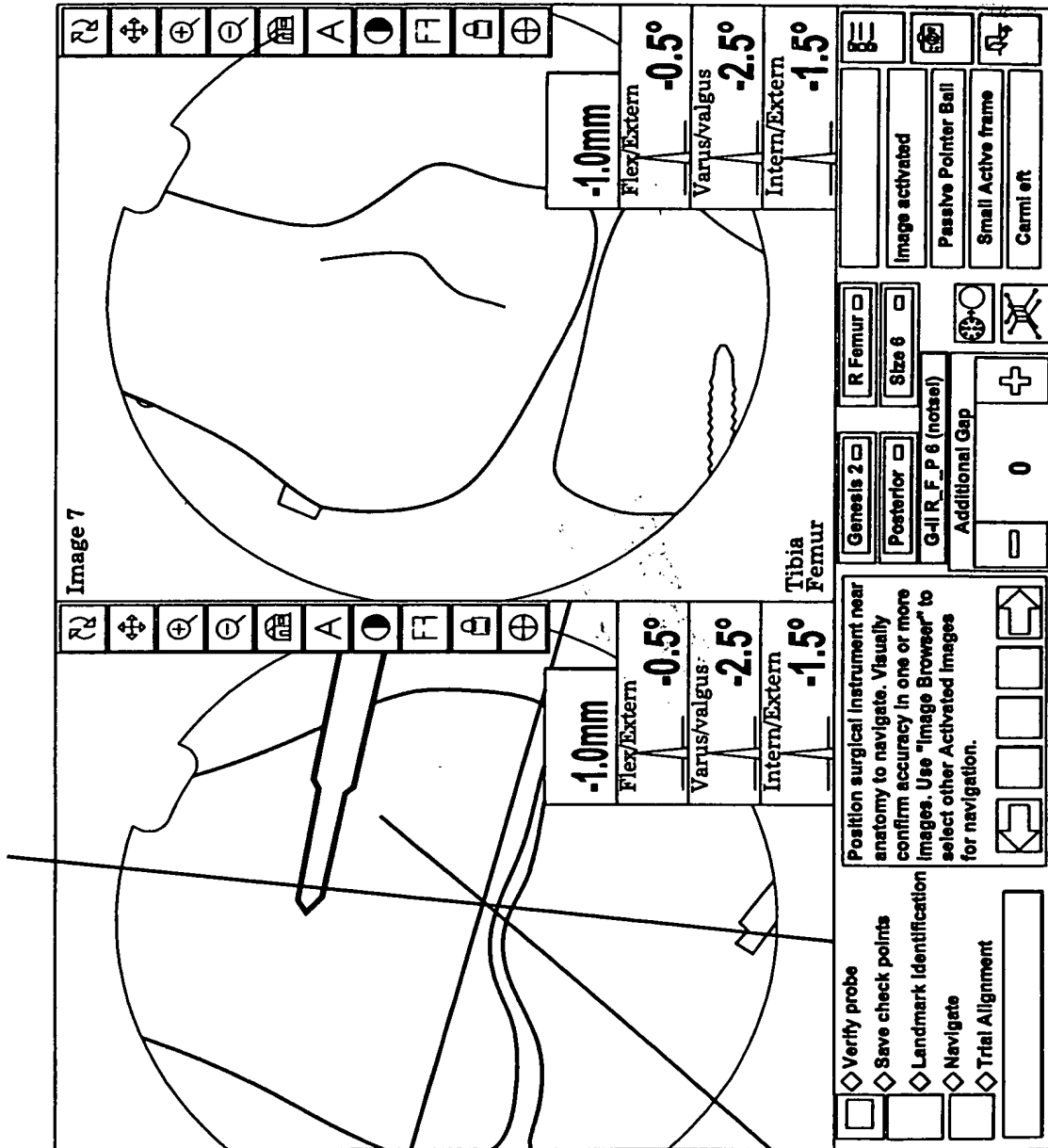


FIG 52

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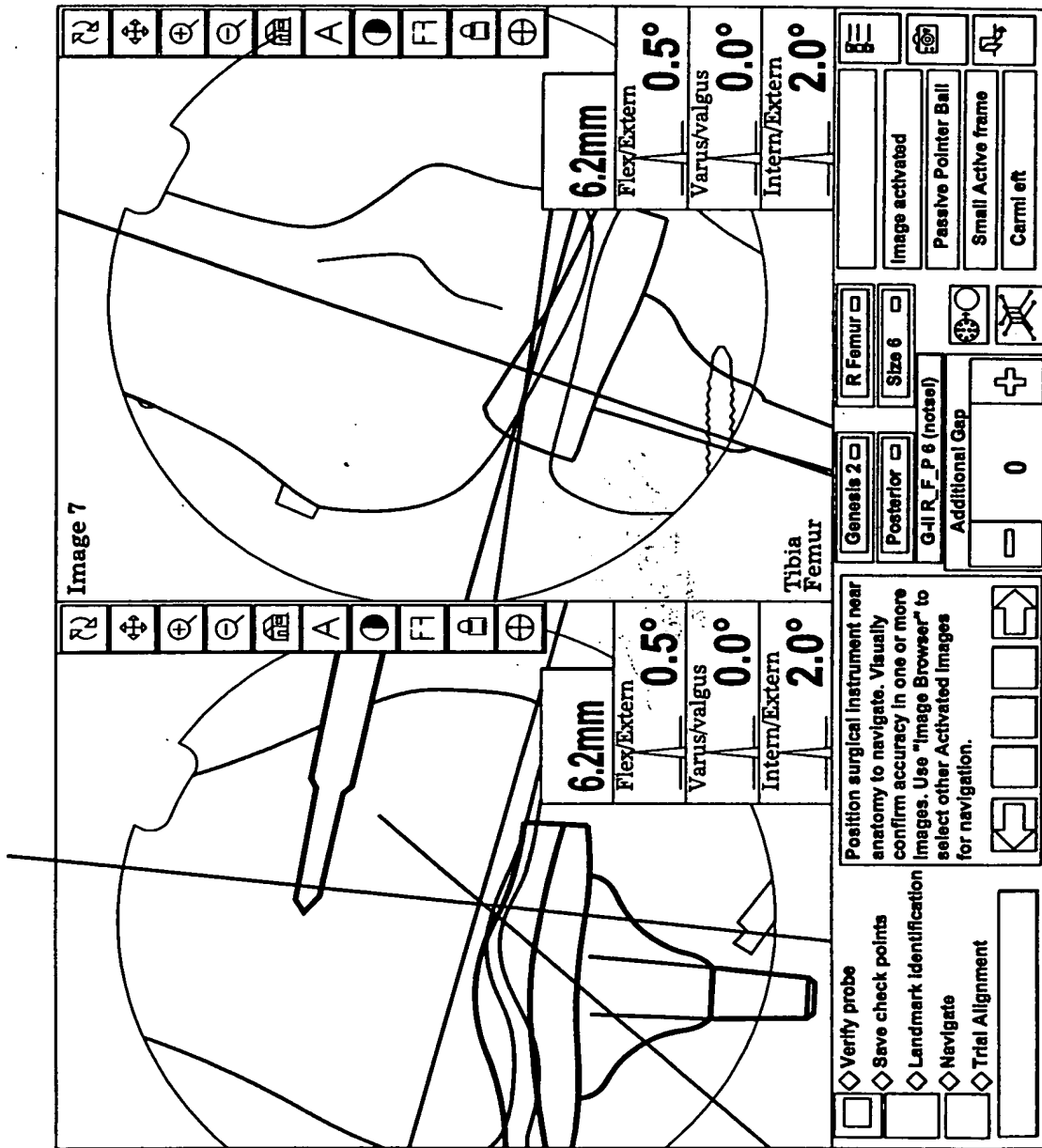
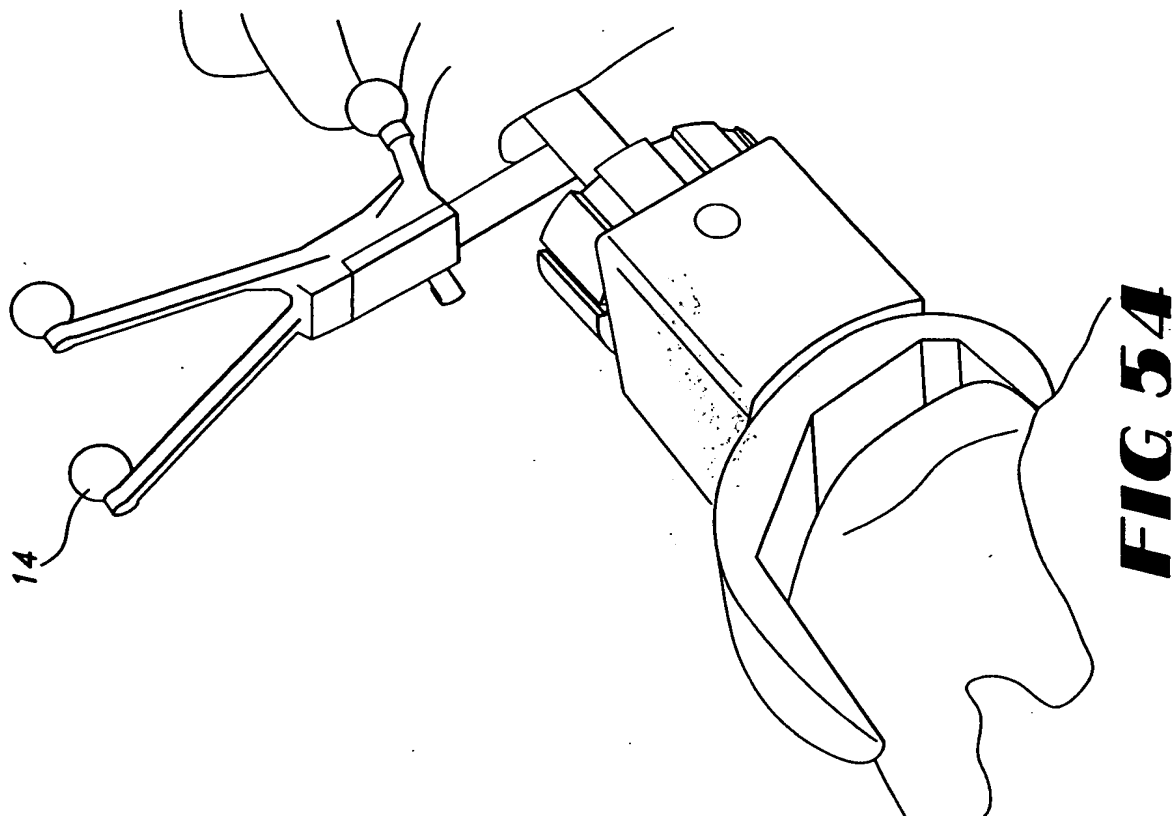
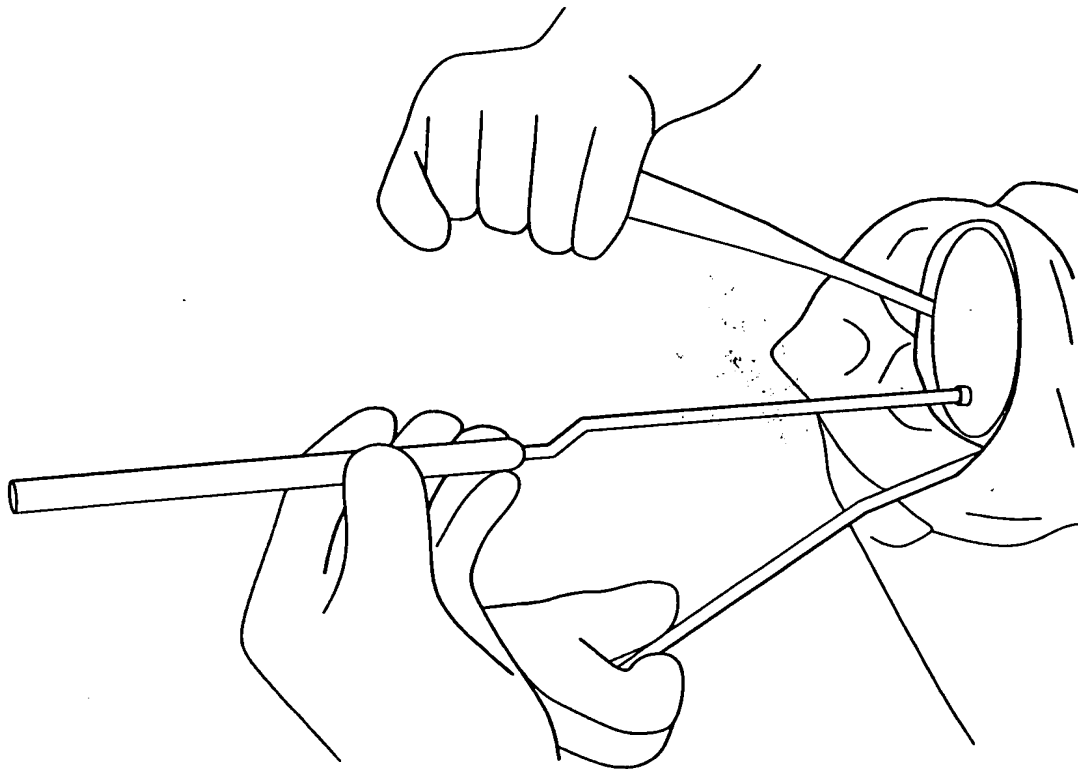


FIG 53

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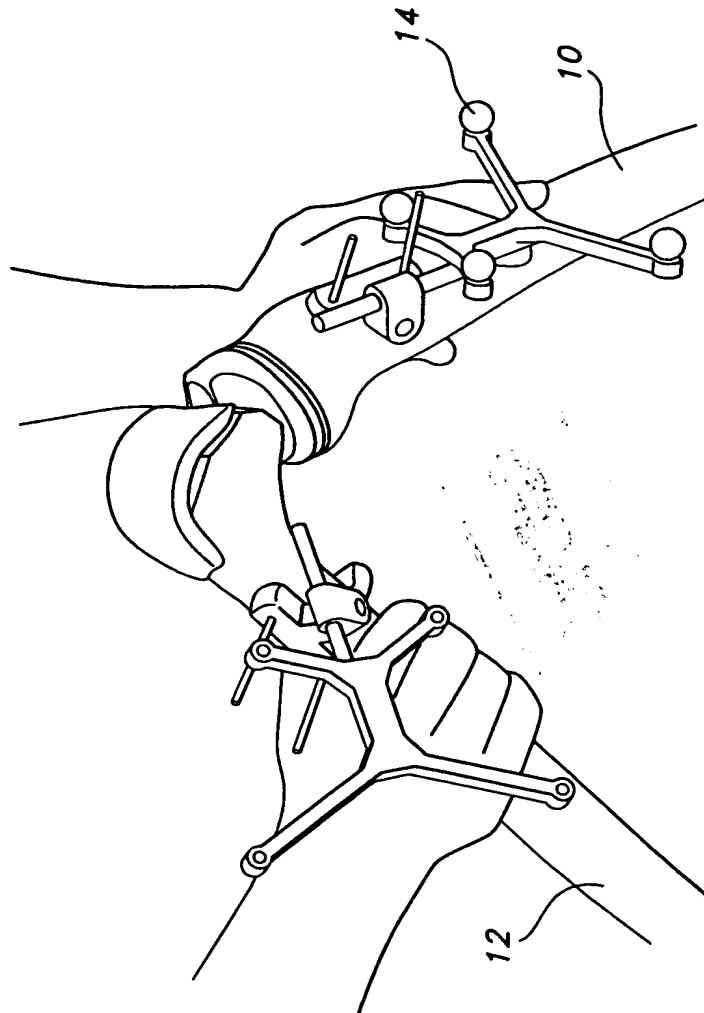


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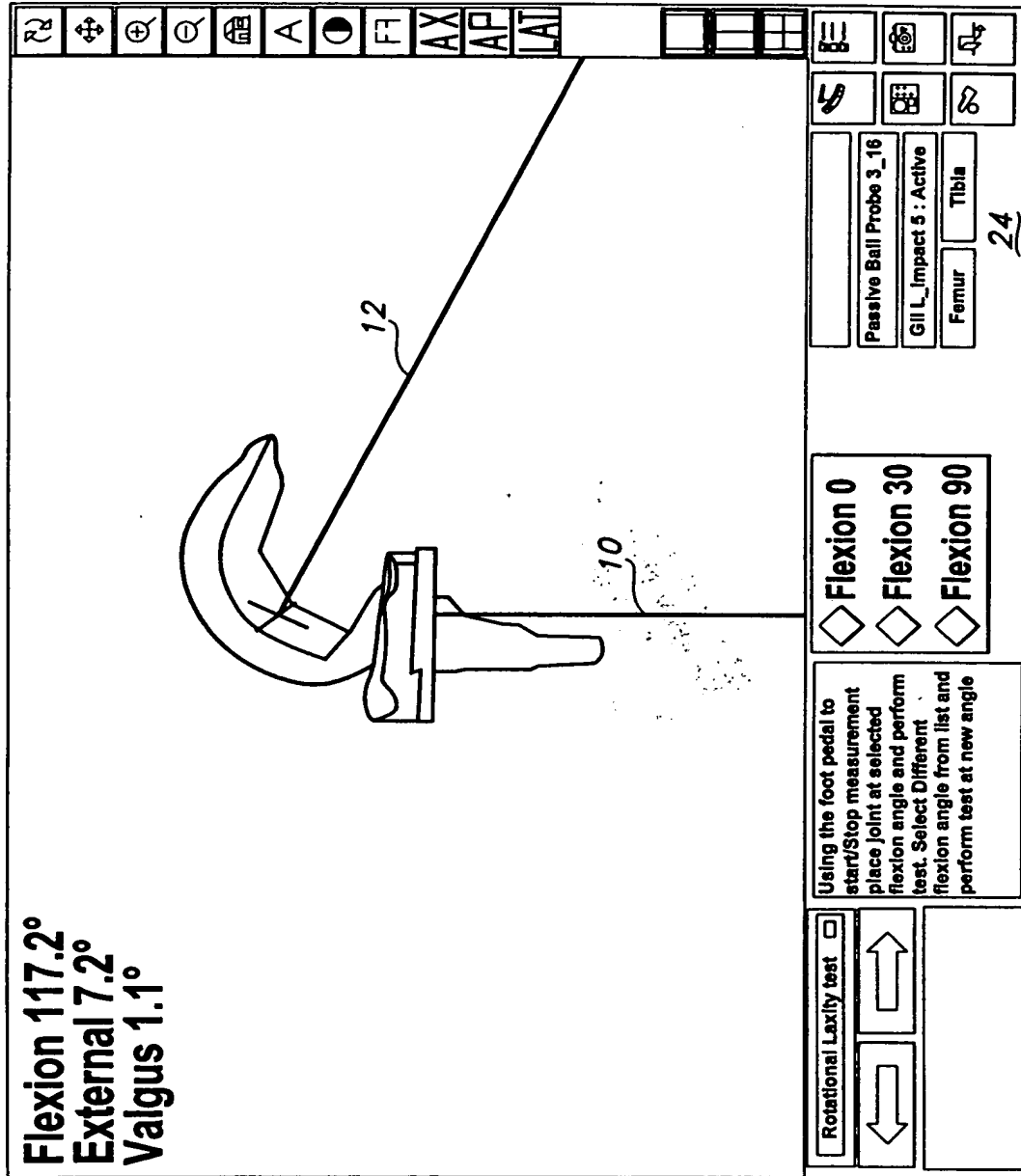


**FIG 55**

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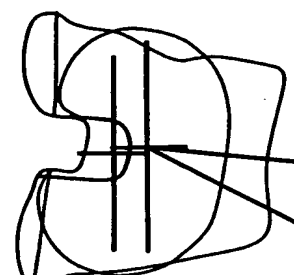
**FIG 57**

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**Flexion 1.3°**  
**Internal 0.8°**  
**Varus 1.0°**

**V/V Medial 0° : 10.7mm**  
**V/V Lateral 0° : 12.2mm**  
**V/V Medial 90° : 14.6mm**  
**V/V Lateral 90° : 14.4mm**

**I/E Rotation 0° : 4.3°**  
**I/E Rotation 90° : 9.0°**



**Flexion 0**  
**Flexion 30**  
**Flexion 90**

Using the foot pedal to start/Stop measurement place joint at selected flexion angle and perform test. Select Different flexion angle from list and perform test at new angle

**Passive Ball Probe 3\_16**  
**Gil L\_Impact 5 : Active**  
**Femur**  
**Tibia**

**24**

**A/P Drawer Test**

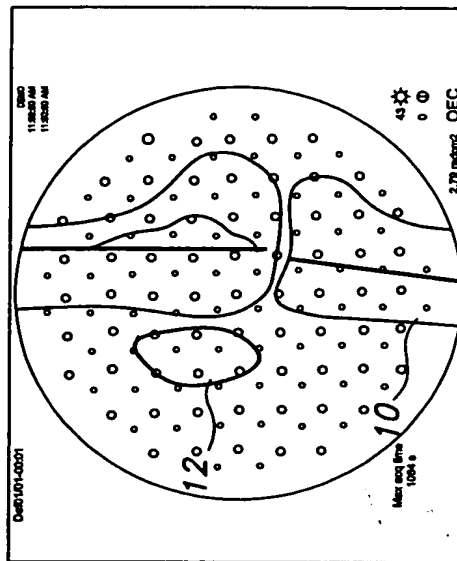
**←**  
**→**

**AX**  
**AP**  
**LAT**

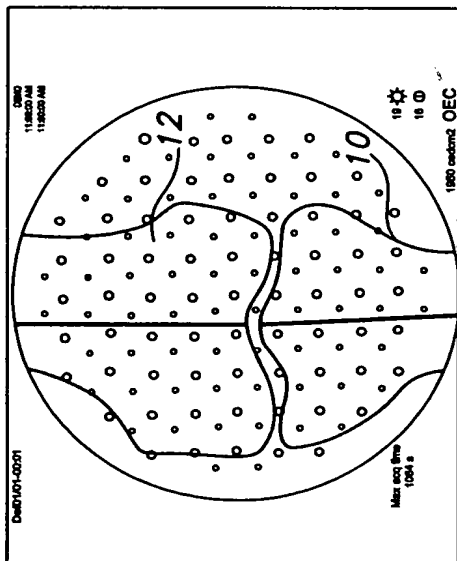
**FIG 58**

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-8°



3°

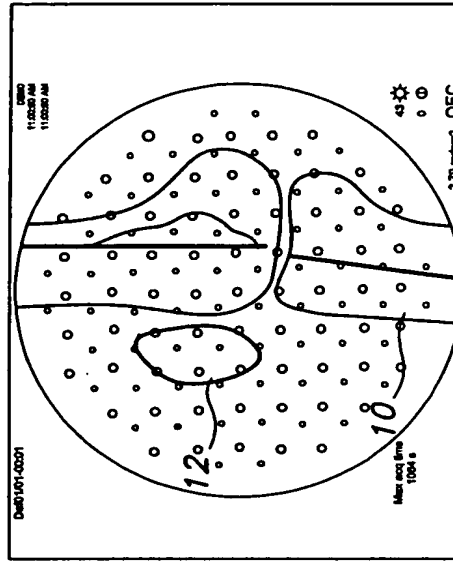


**FIG 60**

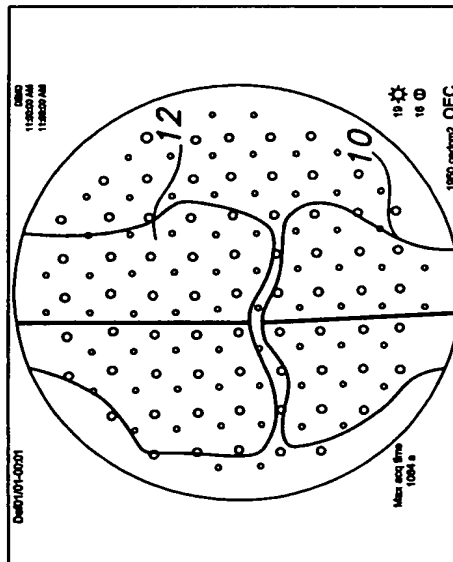


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-8°



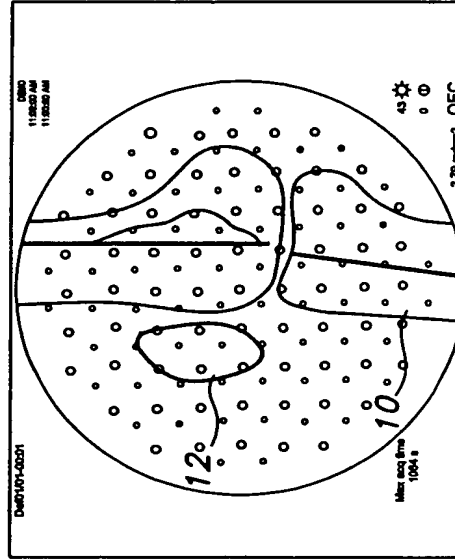
3°



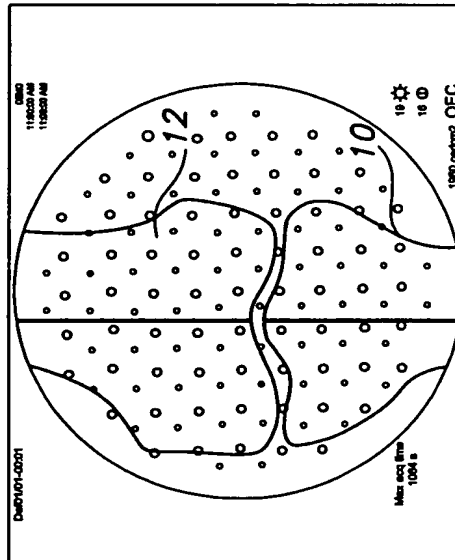
**FIG 61**

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-8°



0°



**FIG 62**

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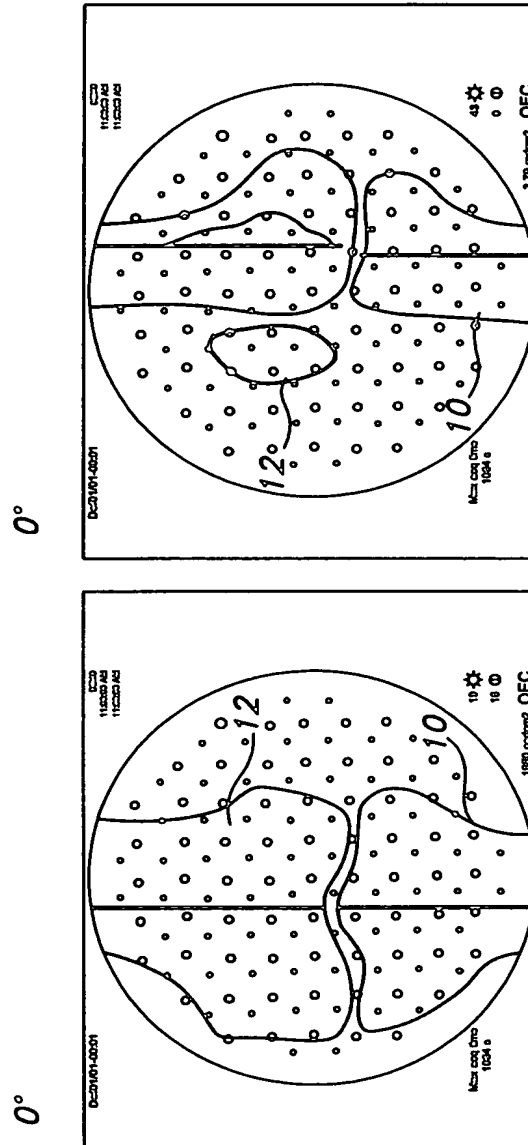


FIG 63

